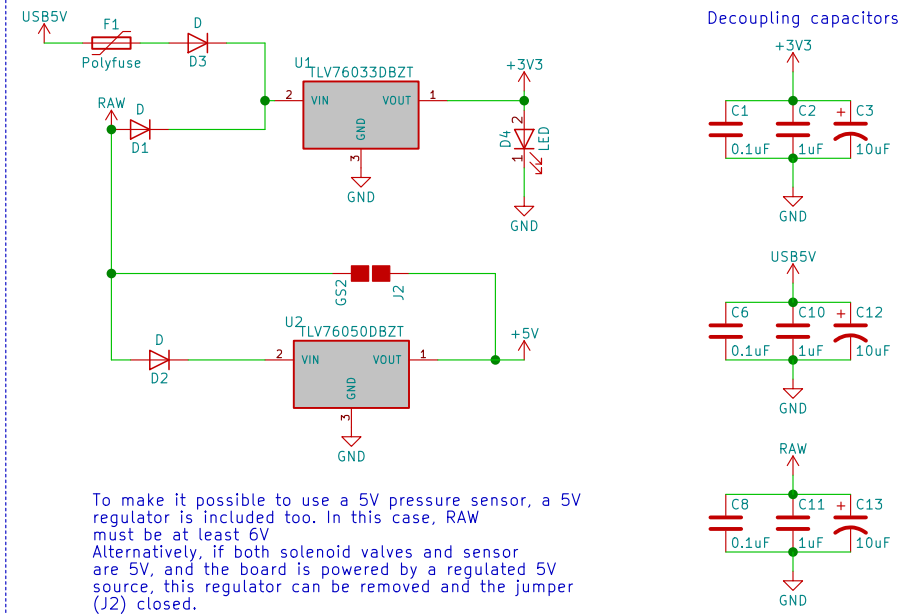


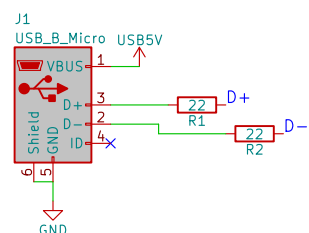
Power

Power input. RAW is 5 to 24VDC, and powers the valves directly. 3.3V regulator powers the microcontroller. 5V regulator powers the sensor, if a 5V sensor is used.

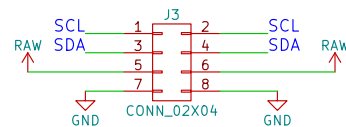


To make it possible to use a 5V pressure sensor, a 5V regulator is included too. In this case, RAW must be at least 6V. Alternatively, if both solenoid valves and sensor are 5V, and the board is powered by a regulated 5V source, this regulator can be removed and the jumper (J2) closed.

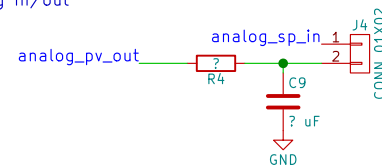
Connectors



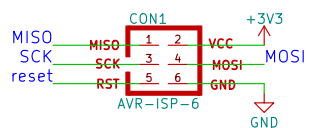
i2c in/out, RAW and GND
2x4 connector to easily daisy-chain several boards



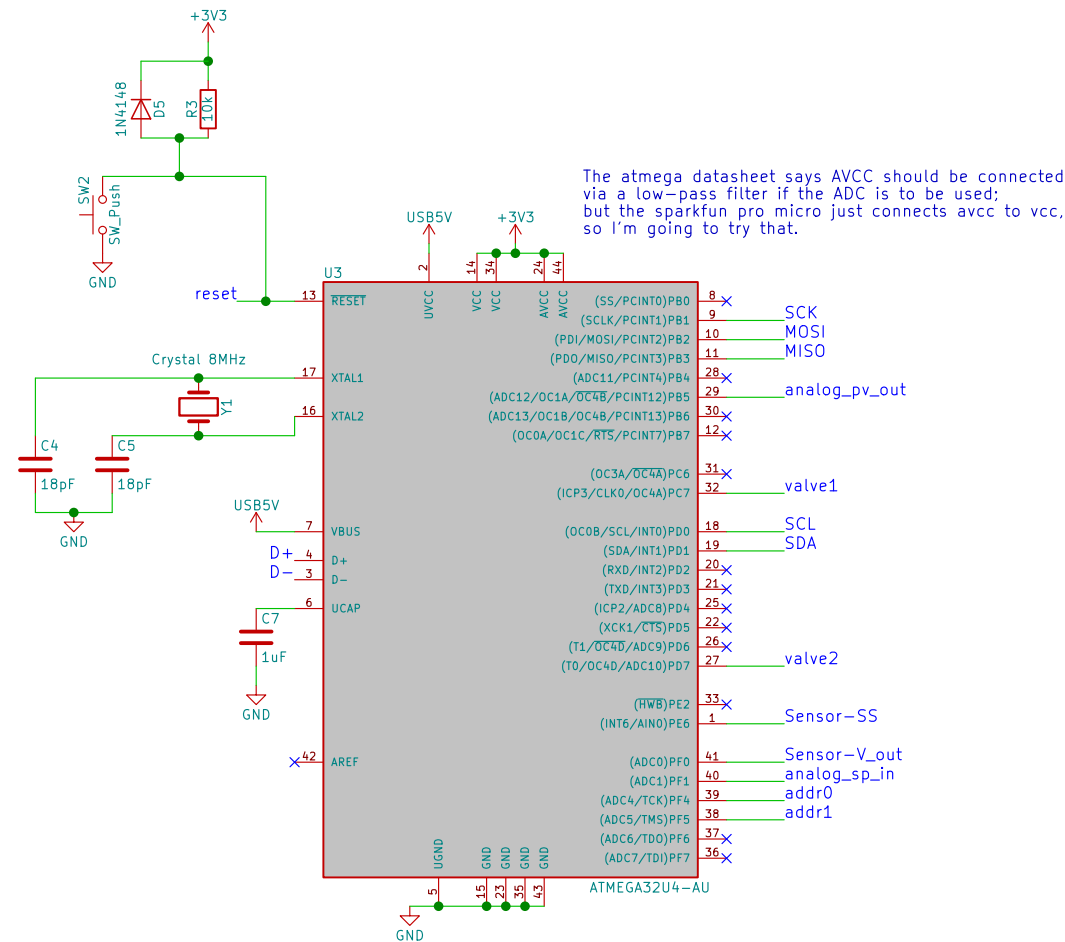
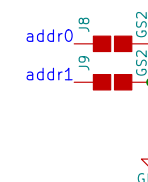
analog in/out



ICSP header for flashing bootloader

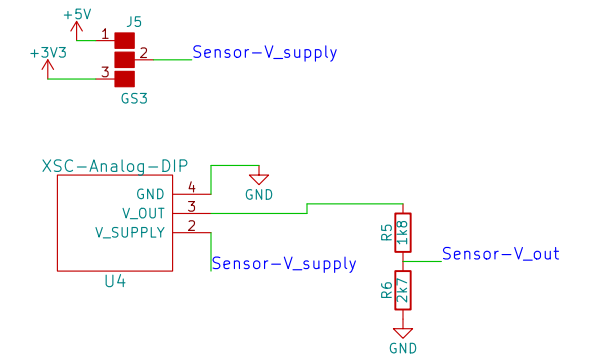


Jumpers for i2c address selection. This will allow up to 4 different addresses without requiring any reprogramming.

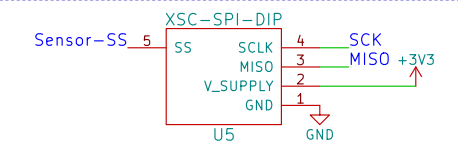


Analog pressure sensor

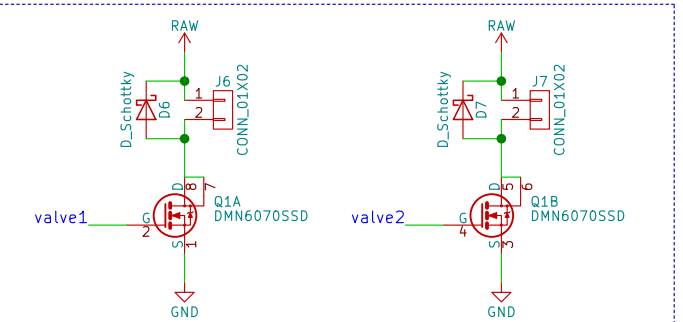
There is support for either a 3.3V or a 5V sensor. For a 3.3V sensor, the resistors are not populated, and the 1k8 resistor is replaced by a solder bridge



Digital pressure sensor



Solenoid valve drivers



Schottky diodes are used due to their very fast recovery times, which is necessary for PWM driving of the valves.

Craig Watson
Senyo Lab
Case Western Reserve University
Sheet: /
File: pressurereg.sch

Title: Pressure regulator

Size: A3 Date: 2018-05-10
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Rev: 1
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