

```
const int motor1Pin1 = 3;
const int motor1Pin2 = 4;
const int enablePin1 = 9;
```

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const int motor2Pin1 = 6;
const int motor2Pin2 = 7;
const int enablePin2 = 12;
```

```
void setup() {
  pinMode(motor1Pin1, OUTPUT);
  pinMode(motor1Pin2, OUTPUT);
  pinMode(enablePin1, OUTPUT);

  pinMode(motor2Pin1, OUTPUT);
  pinMode(motor2Pin2, OUTPUT);
  pinMode(enablePin2, OUTPUT);

  digitalWrite(enablePin1, HIGH);
  digitalWrite(enablePin2, HIGH);
}
void loop() {
  digitalWrite(motor1Pin1, HIGH);
  digitalWrite(motor1Pin2, LOW);
  digitalWrite(motor2Pin1, HIGH);
  digitalWrite(motor2Pin2, LOW);
  delay(2000);

  digitalWrite(motor1Pin1, HIGH);
  digitalWrite(motor1Pin2, HIGH);
  digitalWrite(motor2Pin1, HIGH);
  digitalWrite(motor2Pin2, HIGH);
  delay(4000);
}
```