

The Glasgow Pascal Compiler with vector extensions¹

Paul Cockshott

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Introduction

Pascal[22, 17] is an old programming language whose relative popularity has declined over the years, but like Fortran and C it lends itself to efficient code generation. Vector Pascal was first developed by Turner[36] and Formella[12]. It supports whole array operations in a manner that is similar to Fortran 90. This manual describes the Glasgow Pascal Compiler which supports vector extensions similar to those developed by Turner and Formella, extensions introduced in ISO Extended Pascal[16] and some new extensions.

Modern processors have provision for parallelism in two ways:

1. The Single Instruction-stream Multiple Data-stream (SIMD) model in which a single instruction causes the same mathematical operation to be carried out on several operands, or pairs of operands at the same time. The level of parallelism supported ranges from 2 floating point operations at a time on the older AMD K6 architecture to 8 floating point operations at a time on the Intel AVX architecture.
2. The provision of multiple cores on one chip which execute parallel instructionsets. These may all run the same instructionset as on Intel processors, or run distinct instructionsets as on the IBM Cell chip.

Whilst processor architectures are moving towards greater levels of parallelism, the most widely used programming languages like C, Java and Delphi are structured around a model of computation in which operations take place on a single value at a time. This was appropriate when processors worked this way, but has become an impediment to programmers seeking to make use of the performance offered by multi-media instructionsets. The introduction of SIMD instruction sets[14][29] to Personal Computers potentially provided substantial performance increases, but the ability of most programmers to harness this performance was held back by two factors. The first was the limited availability of compilers that make effective use of these instructionsets in a machine independent manner. The second is the fact that most popular programming languages were designed on the word at a time model of the classic von Neumann computer.

The Glasgow Pascal Compiler aims to provide an efficient and concise notation for programmers using Multi-core and SIMD enhanced CPUs. In doing so it borrows concepts for expressing data parallelism that have a long history, dating back to Iverson's work on APL in the early '60s[18].

Define a vector of type T as having type $T[]$. Then if we have a binary operator $\omega : (T \otimes T) \rightarrow T$, in languages derived from APL we automatically have an operator $\omega : (T[] \otimes T[]) \rightarrow T[]$. Thus if x, y are arrays of integers $k = x + y$ is the array of integers where $k_i = x_i + y_i$.

The basic concept is simple, there are complications to do with the semantics of operations between arrays of different lengths and different dimensions, but Iverson provides a consistent treatment of these. The most recent languages to be built round this model are J, an interpretive language[20][5][21], and F[28] a modernised Fortran. In principle though any language with array types can be extended in a similar way. Iverson's approach to data parallelism is machine independent. It can be implemented using scalar instructions or using the SIMD model. The only difference is speed.

Vector Pascal incorporates Iverson's approach to data parallelism. Its aim is to provide a notation that allows the natural and elegant expression of data parallel algorithms within a base language that is already familiar to a considerable body of programmers and combine this with modern compilation techniques.

By an elegant algorithm I mean one which is expressed as concisely as possible. Elegance is a goal that one approaches asymptotically, approaching but never attaining[7]. APL and J allow the construction of very elegant programs, but at a cost. An inevitable consequence of elegance is the loss of redundancy. APL programs are as concise, or even more concise than conventional mathematical notation[19] and use a special character-set. This makes them hard for the uninitiated to understand. J attempts to remedy this by restricting itself to the ASCII character-set, but still looks dauntingly unfamiliar to programmers brought up on more conventional languages. Both APL and J are interpretive which makes them ill suited to many of the applications for which SIMD speed is required. The aim of the vector extensions in the Glasgow Pascal Compiler is to provide the conceptual gains of Iverson's notation within a framework familiar to imperative programmers.

Pascal[22] was chosen as a base language over the alternatives of C and Java. C was rejected because notations like $x+y$ for x and y declared as `int x[4], y[4]`, already have the meaning of adding the addresses of the arrays together. Java was rejected because of the difficulty of efficiently transmitting data parallel operations via its intermediate code to a just in time code generator.

Iverson's approach to data parallelism is machine independent. It can be implemented using scalar instructions or using the SIMD model. The only difference is speed.

Chapter 1

Elements of the language

1.1 Alphabet

The Glasgow Pascal Compiler accepts files in the UTF-8 encoding of Unicode as source. Since ASCII is a subset of this, ASCII files are valid input.

Pascal programs are made up of letter, digits and special symbols. The letters digits and special symbols are drawn either from a base character set or from an extended character set. The base character set is drawn from ASCII and restricts the letters to be from the Latin alphabet. The extended character set allows letters from other alphabets.

The special symbols used in the base alphabet are shown in table 1.1 .

1.1.1 Extended alphabet

The extended alphabet is described in section 5.1 Using Unicode with Vector Pascal.

1.2 Reserved words

The reserved words are

ABS, ADDR, AND, ARRAY,
BEGIN, BYTE2PIXEL,
CASE, CAST, CDECL, CHR, CONST, COS,
DIV, DO, DOWNT0,
END, ELSE, EXIT, EXTERNAL,

Table 1.1: Special symbols

+	:	(
-	')
*	=	[
/	<>]
:=	<	{
.	<=	}
,	>=	^
;	>	..
+:	@	*)
-:	\$	(*
-	**	

FALSE, FILE, FOR, FUNCTION,
 GOTO,
 IF, IMPLEMENTATION, IN, INTERFACE, IOTA,
 LABEL, LIBRARY, LN,
 MAX, MIN, MOD,
 NAME, NDX, NOT,
 OF, OR, ORD, OTHERWISE,
 PACKED, PERM, PIXEL2BYTE, POW, PRED,
 PROCEDURE, PROGRAM, PROTECTED ,
 RDU, RECORD, REPEAT, ROUND,
 SET, SHL, SHR, SIN, SIZEOF, STRING, SQRT, SUCC,
 TAN, THEN, TO, TRANS, TRUE, TYPE,
 VAR,
 WITH, WHILE, UNIT, UNTIL, USES

Reserved words may be written in either lower case or upper case letters, or any combination of the two.

1.3 Comments

The comment construct

```
{ < any sequence of characters not containing “}” > }
```

may be inserted between any two identifiers, special symbols, numbers or reserved words without altering the semantics or syntactic correctness of the program. The bracketing pair (* *) may substitute for { }. Where a comment starts with { it continues until the next }. Where it starts with (* it must be terminated by *)¹.

1.4 Identifiers

Identifiers are used to name values, storage locations, programs, program modules, types, procedures and functions. An identifier starts with a letter followed by zero or more letters, digits or the special symbol `_`. Case is not significant in identifiers. ISO Pascal allows the Latin letters A-Z to be used in identifiers. The Glasgow Pascal Compiler extends this by allowing symbols from the Greek, Cyrillic, Katakana and Hiragana, or CJK character sets

1.5 Literals

1.5.1 Integer numbers

Integer numbers are formed of a sequence of decimal digits, thus 1, 23, 9976 etc, or as hexadecimal numbers, or as numbers of any base between 2 and 36. A hexadecimal number takes the form of a \$ followed by a sequence of hexadecimal digits thus \$01, \$3ff, \$5A. The letters in a hexadecimal number may be upper or lower case and drawn from the range a..f or A..F.

A based integer is written with the base first followed by a # character and then a sequence of letters or digits. Thus 2#1101 is a binary number 8#67 an octal number and 20#7i a base 20 number.

The default precision for integers is 32 bits².

¹Note this differs from ISO Pascal which allows a comment starting with { to terminate with *) and vice versa.

²The notation used for grammar definition is a tabularised BNF. Each boxed table defines a production, with the production name in the left column. Each line in the right column is an alternative for the production. The metasympol + indicates one or more repetitions of what immediately precedes it. The Kleene star * is used for zero or more repetitions. Terminal symbols are in single quotes. Sequences in brackets [] are optional.

Table 1.2: The hexadecimal digits of Vector Pascal.

Value	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15
Notation 1	0	1	2	3	4	5	6	7	8	9	A	B	C	D	E	F
Notation 2	0	1	2	3	4	5	6	7	8	9	a	b	c	d	e	f

<digit sequence>	<digit> +
<decimal integer>	<digit sequence>
<hex integer>	'\$'<hexdigit>+
<based integer>	<digit sequence>'# '<alphanumeric>+
<unsigned integer>	<decimal integer> <hex integer> <based integer>

1.5.2 Real numbers

Real numbers are supported in floating point notation, thus 14.7, 9.99e5, 38E3, 3.6e-4 are all valid denotations for real numbers. The default precision for real numbers is also 32 bit, though intermediate calculations may use higher precision. The choice of 32 bits as the default precision is influenced by the fact that 32 bit floating point vector operations are well supported in multi-media instructions.

<exp>	'e' 'E'
<scale factor>	[<sign>] <unsigned integer>
<sign>	'-' '+'
<unsigned real>	<decimal integer> '.' <digit sequence> <decimal integer> '.' <digit sequence> <exp><scale factor> <decimal integer><exp> <scale factor>

Fixed point numbers

In the Glasgow Pascal Compiler output code pixels are represented as signed fixed point fractions in the range -1.0 to 1.0. Within this range, fixed point literals have the same syntactic form as real numbers.

1.5.3 Character strings

Sequences of characters enclosed by quotes are called literal strings. Literal strings consisting of a single character are constants of the standard type char. If the string is to contain a quote character this quote character must be written twice.

'A' 'x' 'hello' 'John"s house'

are all valid literal strings. The allowable characters in literal strings are any of the Unicode characters above u0020. The character strings must be input to the compiler in UTF-8 format.

Chapter 2

Declarations

Pascal is a language supporting nested declaration contexts. A declaration context is either a program context, and unit interface or implementation context, or a procedure or function context. A resolution context determines the meaning of an identifier. Within a resolution context, identifiers can be declared to stand for constants, types, variables, procedures or functions. When an identifier is used, the meaning taken on by the identifier is that given in the closest containing resolution context. Resolution contexts are any declaration context or a `with` statement context. The ordering of these contexts when resolving an identifier is:

1. The declaration context identified by any `with` statements which nest the current occurrence of the identifier. These `with` statement contexts are searched from the innermost to the outermost.
2. The declaration context of the currently nested procedure declarations. These procedure contexts are searched from the innermost to the outermost.
3. The declaration context of the current unit or program.
4. The interface declaration contexts of the units mentioned in the use list of the current unit or program. These contexts are searched from the rightmost unit mentioned in the use list to the leftmost identifier in the use list.
5. The interface declaration context of the System unit.
6. The pre-declared identifiers of the language.

2.1 Constants

A constant definition introduces an identifier as a synonym for a constant.

<code><constant declaration></code>	<code><identifier>=<expression></code> <code><identifier>': '<type>'='<typed constant></code>
---	--

Constants can be simple constants or typed constants. A simple constant must be a constant expression whose value is known at compile time. This restricts it to expressions for which all component identifiers are other constants, and for which the permitted operators are given in table2.1 . This restricts simple constants to be of scalar or string types.

Table 2.1: The operators permitted in constant expressions.

+	-	*	/	div	mod	shr	shl	and	or
---	---	---	---	-----	-----	-----	-----	-----	----

Typed constants provide the program with initialised variables which may hold array types.

<typed constant>	<expression> <array constant>
------------------	----------------------------------

2.1.1 Array constants

Array constants are comma separated lists of constant expressions enclosed by brackets. Thus

```
tr:array[1..3] of real =(1.0,1.0,2.0);
is a valid array constant declaration, as is:
t2:array[1..2,1..3] of real=((1.0,2.0,4.0),(1.0,3.0,9.0));
```

The array constant must structurally match the type given to the identifier. That is to say it must match with respect to number of dimensions, length of each dimension, and type of the array elements.

<array constant>	'(' <typed constant> [,<typed constant>]* ')'
------------------	---

2.1.2 Pre-declared constants

`maxint` The largest supported integer value.

`pi` A real numbered approximation to π

`maxchar` The highest character in the character set.

`maxstring` The maximum number of characters allowed in a string.

`maxreal` The highest representable real.

`minreal` The smallest representable positive real number.

`epsreal` The smallest real number which when added to 1.0 yields a value distinguishable from 1.0.

`maxdouble` The highest representable double precision real number.

`mindouble` The smallest representable positive double precision real number.

`complexzero` A complex number with zero real and imaginary parts.

`complexone` A complex number with real part 1 and imaginary part 0.

2.2 Labels

Labels are written as digit sequences. Labels must be declared before they are used. They can be used to label the start of a statement and can be the destination of a `goto` statement. A `goto` statement must have as its destination a label declared within the current innermost declaration context. A statement can be prefixed by a label followed by a colon.

```
Example
label 99;
begin read(x); if x>9 goto 99; write(x*2);99: end;
```

Table 2.2: Categorisation of the standard types.

type	category
real	floating point
double	floating point
byte	integral
pixel	fixed point
shortint	integral
word	integral
integer	integral
cardinal	integral
boolean	scalar
char	scalar

2.3 Types

A type declaration determines the set of values that expressions of this type may assume and associates with this set an identifier.

<type>	<simple type> <structured type> <pointer type>
<type definition>	<identifier>'='<type>

2.3.1 Simple types

Simple types are either scalar, standard, subrange or dimensioned types.

<simple type>	<scalar type> <integral type> <subrange type> <dimensioned type> <floating point type>
---------------	--

Scalar types

A scalar type defines an ordered set of identifier by listing these identifiers. The declaration takes the form of a comma separated list of identifiers enclosed by brackets. The identifiers in the list are declared simultaneously with the declared scalar type to be constants of this declared scalar type. Thus

```
colour = (red,green,blue);
day=(monday,tuesday,wednesday,thursday,
      friday,saturday,sunday);
```

are valid scalar type declarations.

Standard types

The following types are provided as standard in Vector Pascal:

`integer` The numbers are in the range -maxint to +maxint.

`real` These are a subset of the reals constrained by the IEEE 32 bit floating point format.

double	These are a subset of the real numbers constrained by the IEEE 64 bit floating point format.
pixel	These are represented as fixed point binary fractions in the range -1.0 to 1.0.
boolean	These take on the values (<code>false</code> , <code>true</code>) which are ordered such that <code>true</code> > <code>false</code> .
char	These include the characters from <code>chr(0)</code> to <code>charmax</code> . All the allowed characters for string literals are in the type <code>char</code> , but the character-set may include other characters whose printable form is country specific.
pchar	Defined as <code>^char</code> .
byte	These take on the positive integers between 0 and 255.
shortint	These take on the signed values between -128 and 127.
word	These take on the positive integers from 0 to 65535.
cardinal	These take on the positive integers from 0 to 4292967295, i.e., the most that can be represented in a 32 bit unsigned number.
longint	A 32 bit integer, retained for compatibility with Turbo Pascal.
int64	A 64 bit integer.
complex	A complex number with the real and imaginary parts held to 32 bit precision.

Subrange types

A type may be declared as a subrange of another scalar or integer type by indicating the largest and smallest value in the subrange. These values must be constants known at compile time.

<subrange type>	<constant> '..' <constant>
-----------------	----------------------------

Examples: `1..10`, `'a'..'f'`, `monday..thursday`.

Pixels

The *conceptual model* of pixels in Vector Pascal is that they are real numbers in the range `-1.0..1.0`. As a signed representation it lends itself to subtraction. As an unbiased representation, it makes the adjustment of contrast easier. For example, one can reduce contrast 50% simply by multiplying an image by 0.5¹. Assignment to pixel variables in Vector Pascal is defined to be saturating - real numbers outside the range `-1..1` are clipped to it. The multiplications involved in convolution operations fall naturally into place.

The *implementation model* of pixels used in Vector Pascal is of 8 bit signed integers treated as fixed point binary fractions. All the conversions necessary to preserve the monotonicity of addition, the range of multiplication etc, are delegated to the code generator which, where possible, will implement the semantics using efficient, saturated multi-media arithmetic instructions.

¹When pixels are represented as integers in the range `0..255`, a 50% contrast reduction has to be expressed as $((p - 128) \div 2) + 128$.

Dimensioned types

These provide a means by which floating point types can be specialised to represent dimensioned numbers as is required in physics calculations. For example:

```
kms = (mass, distance, time);
meter = real of distance;
kilo = real of mass;
second = real of time;
newton = real of mass * distance * time POW -2;
meterpersecond = real of distance * time POW -1;
```

The grammar is given by:

<dimensioned type>	<real type> <dimension >['*' <dimension>]*
<real type>	'real' 'double'
<dimension>	<identifier> ['POW' [<sign>] <unsigned integer>]

The identifier must be a member of a scalar type, and that scalar type is then referred to as the basis space of the dimensioned type. The identifiers of the basis space are referred to as the dimensions of the dimensioned type. Associated with each dimension of a dimensioned type there is an integer number referred to as the power of that dimension. This is either introduced explicitly at type declaration time, or determined implicitly for the dimensional type of expressions.

A value of a dimensioned type is a dimensioned value. Let $\log_d t$ of a dimensioned type t be the power to which the dimension d of type t is raised. Thus for $t = \text{newton}$ in the example above, and $d = \text{time}$, $\log_d t = -2$

If x and y are values of dimensioned types t_x and t_y respectively, then the following operators are only permissible if $t_x = t_y$

+	-	<	>	<>	=	<=	>=
---	---	---	---	----	---	----	----

For + and -, the dimensional type of the result is the same as that of the arguments. The operations

*	/
---	---

are permitted if the types t_x and t_y share the same basis space, or if the basis space of one of the types is a subrange of the basis space of the other.

The operation POW is permitted between dimensioned types and integers.

Dimension deduction rules

1. If $x = y * z$ for $x : t_1, y : t_2, z : t_3$ with basis space B then

$$\forall_{d \in B} \log_d t_1 = \log_d t_2 + \log_d t_3$$

2. If $x = y / z$ for $x : t_1, y : t_2, z : t_3$ with basis space B then

$$\forall_{d \in B} \log_d t_1 = \log_d t_2 - \log_d t_3$$

3. If $x = y \text{ POW } z$ for $x : t_1, y : t_2, z : \text{integer}$ with basis space for t_2 , B then

$$\forall_{d \in B} \log_d t_1 = \log_d t_2 \times z$$

2.3.2 Structured types

Static Array types

An array type is a structure consisting of a fixed number of elements all of which are the same type. The type of the elements is referred to as the element type. The elements of an array value are indicated by bracketed indexing expressions. The definition of an array type simultaneously defines the permitted type of indexing expression and the element type.

The index type of a static array must be a scalar or subrange type. This implies that the bounds of a static array are known at compile time.

<array type>	'array' '[' <index type>[,<index type>]* ']' 'of' <type>
<index type>	<subrange type> <scalar type> <integral type>

Examples

```
array[colour] of boolean;
array[1..100] of integer;
array[1..2,4..6] of byte;
array[1..2] of array[4..6] of byte;
```

The notation $[b,c]$ in an array declaration is shorthand for the notation $[b]$ of array $[c]$. The number of dimensions of an array type is referred to as its rank. Scalar types have rank 0.

String types

A string type denotes the set of all sequences of characters up to some finite length and must have the syntactic form:

<string-type>	'string[' <integer constant>']' 'string' 'string(' <integer constant>')
---------------	---

the integer constant indicates the maximum number of characters that may be held in the string type. The maximum number of characters that can be held in any string is indicated by the pre-declared constant `maxstring`. The type `string` is shorthand for `string[maxstring]`.

Record types

A record type defines a set of similar data structures. Each member of this set, a record instance, is a Cartesian product of number of components or *fields* specified in the record type definition. Each field has an identifier and a type. The scope of these identifiers is the record itself.

A record type may have as a final component a *variant part*. The variant part, if a variant part exists, is a union of several variants, each of which may itself be a Cartesian product of a set of fields. If a variant part exists there may be a tag field whose value indicates which variant is assumed by the record instance.

All field identifiers even if they occur within different variant parts, must be unique within the record type.

<record type>	'record' <field list> 'end'
<field list>	<fixed part> <fixed part>;' <variant part> <variant part>
<fixed part>	<record section> [';' <record section.]*
<record section>	<identifier>[';' <identifier>]* ':' <type> <empty>
<variant part>	'case' [<tag field> ':'] <type identifier> 'of' <variant>[';' <variant>]*
<variant>	<constant> [';' <constant>]* ':' '(' <field list> ')' <empty>

Set types

A set type defines the range of values which is the power-set of its base type. The base type must be an ordered type, that is a type on which the operations $<$, $=$ and $>$ are defined². Thus sets may be declared whose base types are characters, numbers, ordinals, or strings. Any user defined type on which the comparison operators have been defined can also be the base type of a set.

<set type>	'set' 'of' <base type>
------------	------------------------

2.3.3 Dynamic types

Variables declared within the program are accessed by their identifier. These variables exist throughout the existence of the scope within which they are declared, be this unit, program or procedure. These variables are assigned storage locations whose addresses, either absolute or relative to some register, can be determined at compile time. Such locations are referred to as static³. Storage locations may also be allocated dynamically. Given a type t , the type of a pointer to an instance of type t is t .

A pointer of type t can be initialised to point to a new store location on the heap of type t by use of the built in procedure *new*. Thus if $p: ^t$,

```
new(p);
```

causes p to point at a store location of type t . The space can be freed by calling *dispose(p)*. If garbage collection is enabled at compile time, freeing of store is automatic. By default garbage collection is off.

Pointers to dynamic arrays

The types pointed to by pointer types can be any of the types mentioned so far, that is to say, any of the types allowed for static variables. In addition however, pointer types can be declared to point at dynamic arrays.

A dynamic array is an array whose bounds are determined at run time.

Pascal 90[16] introduced the notion of schematic or parameterised types as a means of creating dynamic arrays. Thus where r is some integral or ordinal type one can write

```
type z(a,b:r)=array[a..b] of t;
```

If $p: ^z$, then

²ISO Pascal requires the base type to be a scalar type, a character type, integer type or a subrange thereof. When the base type is one of these, Vector Pascal implements the set using bitmaps. When the type is other than these, balanced binary trees are used. It is strongly recommended that use be made of Boehm garbage collector (see section ??) if non-bitmapped sets are used in a program.

³The Pascal concept of static variables should not be equated with the notion of static variables in some other languages such as C or Java. In Pascal a variable is considered static if its offset either relative to the stack base or relative to the start of the global segment can be determined at compile/link time. In C a variable is static only if its location relative to the start of the global segment is known at compile time.

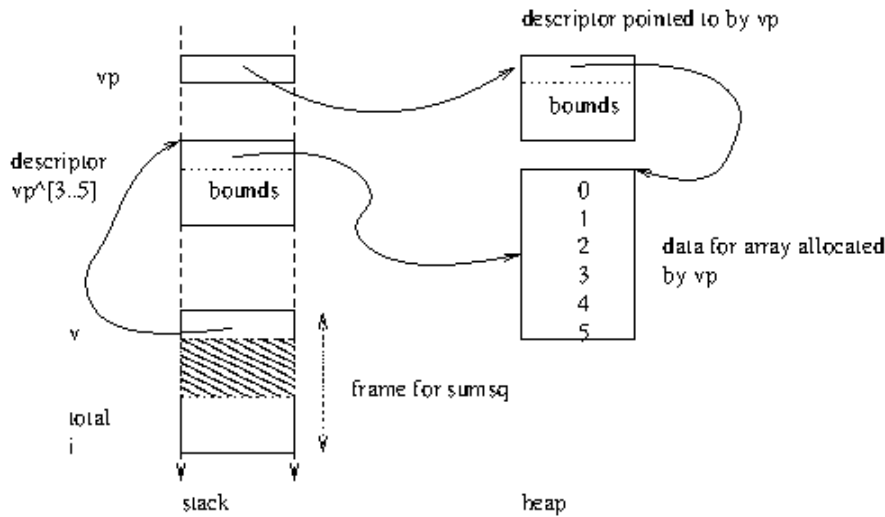


Figure 2.1: How dynamic arrays are implemented

```
new(p, n, m)
```

where $n, m: r$ initialises p to point to an array of bounds $n..m$. The bounds of the array can then be accessed as p^a , p^b . In this case a, b are the formal parameters of the array type. Vector Pascal currently only allows parameterised types to be allocated on the heap via `new`. The extended form of the procedure `new` must be passed an actual parameter for each formal parameter in the array type. Dynamic array types can be used to allow slices of arrays to be passed as parameters to functions as shown here:

```
type vector(a:integer)=array[0..a] of integer;
pv=^vector;
function sumsq ( var v:vector):integer;
var total,i:integer;
begin
  total:=0;
  for i:=0 to v.a do total:= total+ v[i]*v[i];
  sumsq:=total;
end;
var vp:pv;
begin
  new (vp, 6);
  vp:=iota[0];
  writeln(sumsq (vp^[3..5]));
```

When using schematic array types in this way, one must take care to pass the array as a var parameter. This is because, unlike static arrays which are simply copied on the stack when passed as value parameters, the compiler can not pre-allocate space on the call stack for a schematic array. This means that you must pass them by reference as a var parameter. Schematic arrays are implemented as descriptors to the actual arrays.

Aliases

In addition to being able to implicitly alias parts of arrays when passing them to procedures the same effect can be achieved by the built in procedure `alias`.

```
type vector(a:integer)=array[1..a] of integer;
```

```

    pv:=^vector;
var vp,p:pv;
begin
    new (vp,6);
    vp^:=iota[0];
    alias(p,vp^[3..5]);
    (* now vp^[3]= p^[1] *)

```

The `alias` procedure takes as its first parameter a pointer to a schematic array, and as its second parameter an array section. The types of the schematic array and the array section must match. It initialises the array pointer to point to a new descriptor on the heap of the array section. This new descriptor occupies heap space, and if garbage collection is not enabled it should be discarded using `dispose` when it is no longer needed.

Delphi style arrays

Vector Pascal also allows the use of Delphi style declarations for dynamic arrays. Thus one can declare:

```

type vector = array of real;
    matrix = array of array of real;

```

The size of such arrays has to be explicitly initialised at runtime by a call to the library procedure `setlength`. Thus one might have:

```

function readtotal:real;
var len:integer;
    v:vector;
begin
    readln(len);
    setlength(v,len);
    readln(v);
    readtotal := \+ v;
end;

```

The function `readtotal` reads the number of elements in a vector from the standard input. It then calls `setlength` to initialise the vector length. Next it reads in the vector and computes its total using the reduction operator `\+`.

Delphi style arrays are implemented as pointers. In the example, the variable `v` denotes an array of reals not a pointer to an array of reals. That is to say you do not have to explicitly dereference `v` using `^`. However, since the array size is not known at compile time `setlength` will allocate space for the array on the heap not in the local stack frame. The use of `setlength` is thus restricted to programs which have been compiled with the garbage collection flag enabled (see section ??). The procedure `setlength` must be passed a parameter for each dimension of the dynamic array. The bounds of the array `a` formed by `setlength(a,i,j,k)` would then be `0..i-1, 0..j-1, 0..k-1`.

Low and High

The built in functions `low` and `high` return the lower and upper bounds of an array respectively. They work with both static and dynamic arrays. Consider the following examples.

```

program arrays;
type z(a,b:integer)=array[a..b] of real;
    vec = array of real;

```

```

        line= array [1..80] of char;
        matrix = array of array of real;
var i:^z; v:vec; l:line; m:matrix;
begin
  setlength(v,10);setlength(m,5,4);
  new(i,11,13);
  writeln(low(v), high(v));
  writeln(low(m), high(m));
  writeln(low(m[0]),high(m[0]));
  writeln(low(l),high(l));
  writeln(low(i^),high(i^));
end.

```

would print

```

        0          9
        0          4
        0          3
        1         80
        11        13

```

2.3.4 Class types

The simplest form of class type is similar to a record. Consider the following example:

```

type A= class
  f1:integer;
end;
B=class(A)
  f2:real;
end;
var c1,anA:A;c2:B;d:boolean;
begin
  new(c1);
  new(c2);
  c1^.f1:=1;
  c1.f1:=2;
  anA:=c2;
  c2.f1:= 1+ c1^.f1;
  d:=(c1.f1+c2.f1)<>5 ;

```

At the end of the above code `d` is false. The example declares two classes `A` with field `f1` and class `B` which has fields `f1` and `f2`. The construct `(A)` in the header of `B` indicates that it inherits all the fields of `A`.

When a variable of a class type is explicitly declared, what is actually being declared is a pointer to an instance of that class. The pointer must be initialised using `new` as shown. Fields can be accessed using the same `.` notation used for record fields except that for classes the `^` for pointer dereference can be optionally elided. The ability to elide the pointer dereference operator for class instances is a feature inherited from the syntax of Delphi.

Note that in the example the variable `anA` must point to an instance of class `A` but it is valid to assign to it a pointer to an instance of class `B` since an instance of class `B` contains all the fields that a class `A` instance contains.

Classes can contain procedure and function header declarations as shown in the next example. The function or procedure itself must be declared lower down within the scope

in which the class itself is declared⁴. When declaring a procedure belonging to a class, the name of the procedure must be prepended by the class name followed by a full-stop.

```
program classdemo;
type A= class
    f1:integer;
    function hello:boolean;
end;
var c1:A;
function A.hello:boolean;
begin
    writeln('hello from class A with a method');
    hello:=true;
end;
```

The functions or procedures declared within a class can be invoked by prepending the function or procedure name with the class instance variable followed by a fullstop:

```
begin
    new(c1);
    c1.f1:=2;
    if not c1.hello then
        writeln('this will never be written')
end.
```

Procedures or functions implementing headers declared within a class have access to the fields of the class instance that they belong to. Within the procedure, names declared in the class appear to be in an immediately enclosing scope as shown below.

```
type A= class
    f1:integer;
    function hello:boolean;
end;
var c1:A;
    i:integer;
function a.hello:boolean;
begin
    hello:=f1=i;
end;
begin
    new(c1);
    c1.f1:=2;
    i:=c1.f1;
    if not c1.hello then { something is very wrong }
```

The function `hello` in `A` has access to the field `f1`.

If a class `B` has a procedure with the same name as one in class `A` then the procedure in `B` will override the one in `A` as shown:

```
type A= class
    f1:integer;
    function hello:boolean;
end;
    B= class (A)
```

⁴This is analogous to the way interfaces of units may contain procedure headers (see Chapter 4).

```

        f2:integer;
        function hello:boolean;
        end;
var c1:b;
    i:integer;
function A.hello:boolean;
begin
    writeln('this will not be called ');
    hello:=false;
end;
function B.hello:boolean;
begin
    hello:=f1=i;
end;
begin
    new(c1);
    c1.f1:=2;
    i:=c1.f1;
    if c1.hello then
        writeln('inheritance works as expected');
    end.

```

Protected, Public, Private, Virtual

The above keywords from Delphi are accepted by the Vector Pascal compiler but ignored. In essence all procedures and functions in classes are assumed to be virtual in the Delphi sense.

2.3.5 File types

A type may be declared to be a file of a type. This form of definition is kept only for backward compatibility. All file types are treated as being equivalent. A file type corresponds to a handle to an operating system file. A file variable must be associated with the operating system file by using the procedures `assign`, `rewrite`, `append`, and `reset` provided by the system unit. A pre-declared file type `text` exists.

Text files are assumed to be in Unicode UTF-8 format. Conversions are performed between the internal representation of characters and UTF-8 on input/output from/to a text file.

2.4 Variables

Variable declarations consist of a list of identifiers denoting the new variables, followed by their types.

<variable declaration>	<identifier> [',' <identifier>]* ':' <type><extmod>
------------------------	---

Variables are abstractions over values. They can be either simple identifiers, components or ranges of components of arrays, fields of records or referenced dynamic variables.

<variable>	<identifier>
	<indexed variable>
	<indexed range>
	<field designator>
	<referenced variable>

Examples

```
x, y: real;
i: integer;
point: ^real;
dataset: array[1..n] of integer;
twoDdata: array[1..n, 4..7] of real;
```

2.4.1 External Variables

A variable may be declared to be external by appending the external modifier.

<extmod>	';' 'external' 'name' <stringlit>
----------	-----------------------------------

This indicates that the variable is declared in a non Vector Pascal external library. The name by which the variable is known in the external library is specified in a string literal.

Example

```
count: integer; external name '_count';
```

2.4.2 Entire Variables

An entire variable is denoted by its identifier. Examples *x*, *y*, *point*,

2.4.3 Indexed Variables

A component of an *n* dimensional array variable is denoted by the variable followed by *n* index expressions in brackets.

<indexed variable>	<variable> '[' <expression> '[' , <expression>]* ']'
--------------------	--

The type of the indexing expression must conform to the index type of the array variable. The type of the indexed variable is the component type of the array.

Examples

```
twoDdata[2, 6]
dataset[i]
```

Given the declaration

```
a=array[p] of q
```

then the elements of arrays of type *a*, will have type *q* and will be identified by indices of type *p* thus:

```
b[i]
```

where *i*:*p*, *b*:*a*.

Given the declaration

```
z = string[x]
```

for some integer $x \leq \text{maxstring}$, then the characters within strings of type *z* will be identified by indices in the range 1..*x*, thus:

```
y[j]
```

where *y*:*z*, *j*:1..*x*.

Indexed Ranges

A range of components of an array variable are denoted by the variable followed by a range expression in brackets.

<indexed range>	<variable> '[' <range expression> '[' , <range expression>]* ']'
<range expression>	<expression> '..' <expression>

The expressions within the range expression must conform to the index type of the array variable. The type of a range expression `a[i..j]` where `a: array[p..q]` of `t` is `array[0..j-i]` of `t`.

Examples:

```
dataset[i..i+2]:=blank;
twoDdata[2..3,5..6]:=twoDdata[4..5,11..12]*0.5;
```

Subranges may be passed in as actual parameters to procedures whose corresponding formal parameters are declared as variables of a schematic type. Hence given the following declarations:

```
type image(miny,maxy,minx,maxx:integer)=array[miny..maxy,minx..maxx]
of byte;
procedure invert(var im:image);begin im:=255-im; end;
var screen:array[0..319,0..199] of byte;
then the following statement would be valid:
invert(screen[40..60,20..30]);
```

Indexing arrays with arrays

If an array variable occurs on the right hand side of an assignment statement, there is a further form of indexing possible. An array may be indexed by another array. If `x:array[t0]` of `t1` and `y:array[t1]` of `t2`, then `y[x]` denotes the virtual array of type `array[t0]` of `t2` such that `y[x][i]=y[x[i]]`. This construct is useful for performing permutations. To fully understand the following example refer to sections 3.1.3,3.2.1.

Example Given the declarations

```
const perms:array[0..3] of integer=(3,1,2,0);
var ma,m0:array[0..3] of integer;
then the statements
m0:= (iota 0)+1;
write('m0=');for j:=0 to 3 do write(m0[j]);writeln;
ma:=m0[perms];
write('perms=');for j:=0 to 3 do write(perms[j]);writeln;
writeln('ma:=m0[perms]');for j:=0 to 3 do write(ma[j]);writeln;
would produce the output
```

```
m0= 1 2 3 4
perms= 3 1 2 0
ma:=m0[perms]
4 2 3 1
```

This basic method can also be applied to multi-dimensional array. Consider the following example of an image warp:

```
type pos      = 0..255;
image        = array[pos,pos] of pixel;
warper       = array[pos,pos,0..1] of pos;
var im1 ,im2 :image;
warp         :warper;
begin
....
getbackwardsarp(warp);
im2 := im1 [ warp ];
....
```

The procedure `getbackwardswarp` determines for each pixel position x, y in an image the position in the source image from which it is to be obtained. After the assignment we have the postcondition

$$\text{im2}[x, y] = \text{im1}[\text{warp}[x, y, 0], \text{warp}[x, y, 1]] \forall x, y \in \text{pos}$$

2.4.4 Field Designators

A component of an instance of a record type, or the parameters of an instance of a schematic type are denoted by the record or schematic type instance followed by the field or parameter name.

<field designator>	<variable>.'<identifier>
--------------------	--------------------------

2.4.5 Referenced Variables

If $p : ^t$, then p^{\wedge} denotes the dynamic variable of type t referenced by p .

<referenced variable>	<variable> '^'
-----------------------	----------------

2.5 Procedures and Functions

Procedure and function declarations allow algorithms to be identified by name and have arguments associated with them so that they may be invoked by procedure statements or function calls.

<procedure declaration>	<procedure heading>';' [<proc tail>]
<proc tail>	'forward' 'external' ['name' <string>] <block>
<paramlist>	'(' <formal parameter sec> [';' <formal parameter sec>] '*')'
<procedure heading>	'procedure' <identifier> [<paramlist>] 'function' <identifier> [<paramlist>] ':' <type>
<formal parameter sec>	['var'] <identifier> [',' <identifier>] ':' <type> <procedure heading>
<procedure type>	'procedure' [<paramlist>] 'function' [<paramlist>] ':' <type>

The parameters declared in the procedure heading are local to the scope of the procedure. The parameters in the procedure heading are termed formal parameters. If the identifiers in a formal parameter section are preceded by the word `var`, then the formal parameters are termed variable parameters. The block⁵ of a procedure or function constitutes a scope local to its executable compound statement. Within a function declaration there must be at least one statement assigning a value to the function identifier. This assignment determines the result of a function, but assignment to this identifier does not cause an immediate return from the function.

Function return values can be scalars, pointers, records, strings, static arrays or sets. Arrays whose size is determined at run time may not be returned from a function.

Where a procedure is declared as `forward` it must be followed by a full definition of procedure lower in the current scope.

The external declaration form allows calls to be made to libraries written in other languages.

⁵see section 4.

Examples The function `sba` is the mirror image of the `abs` function.

```
function sba(i:integer):integer;
begin if i>0 then sba:=-i else sba:=i end;
type stack:array[0..100] of integer;
procedure push(var s:stack;i:integer);
begin s[s[0]]:=i;s[0]:=s[0]+1; end;

procedure append(var f:fileptr);external;
procedure close      (var f:fileptr); external name 'pascalclose';
```

2.5.1 Procedural Parameters to Procedures

A procedure may have parameters that are themselves procedures as shown in the following example.

```
program CONF103(output);
var
  i : integer;
procedure alsoconforms(x : integer);
begin
  writeln(' PASS...6.6.3.1-4 (CONF103)')
end;
procedure conforms(procedure alsoconforms(x : integer));
  var x : boolean;
begin
  x:=true;
  alsoconforms(1)
end;
begin
  i:=2;
  conforms(alsoconforms)
end.
```

2.5.2 Procedure types

Procedural types may be declared. This in turn allows procedure variables. These store the address of a procedure or function and can be assigned to using the address operator `@`.

Example

```
program procvar;
type t=procedure (x:integer);
var v:t;
  procedure f(a:integer);begin writeln(a);end;
begin
  v:= @f;
  v(3);
end.
```

Chapter 3

Algorithms

3.1 Expressions

An expression is a rule for computing a value by the application of operators and functions to other values. These operators can be *monadic* - taking a single argument, or *dyadic* - taking two arguments.

3.1.1 Mixed type expressions

The arithmetic operators are defined over the base types integer and real. If a dyadic operator that can take either real or integer arguments is applied to arguments one of which is an integer and the other a real, the integer argument is first implicitly converted to a real before the operator is applied. Similarly, if a dyadic operator is applied to two integral numbers of different precision, the number of lower precision is initially converted to the higher precision, and the result is of the higher precision. Higher precision of types t, u is defined such that the type with the greater precision is the one which can represent the largest range of numbers. Hence reals are taken to be higher precision than longints even though the number of significant bits in a real may be less than in a longint.

When performing mixed type arithmetic between pixels and another numeric data type, the values of both types are converted to reals before the arithmetic is performed. If the result of such a mixed type expression is subsequently assigned to a pixel variable, all values greater than 1.0 are mapped to 1.0 and all values below -1.0 are mapped to -1.0.

3.1.2 Primary expressions

<primary expression>	'(<expression>)' <literal string> 'true' 'false' <unsigned integer> <unsigned real> <variable> <constant id> <function call> <set construction>
----------------------	--

The most primitive expressions are instances of the literals defined in the language: literal strings, boolean literals, literal reals and literal integers. 'Salerno', true, 12, \$ea8f, 1.2e9 are all primary expressions. The next level of abstraction is provided by symbolic

identifiers for values. `X`, `left`, `a.max`, `p^.next`, `z[1]`, `image[4..200,100..150]` are all primary expressions provided that the identifiers have been declared as variables or constants.

An expression surrounded by brackets () is also a primary expression. Thus if e is an expression so is (e) .

<function call>	<function id> ['(' <expression> [,<expression>]* ')']
<element>	<expression> <range expression>

Let e be an expression of type t_1 and if f is an identifier of type $\text{function}(t_1) : t_2$, then $f(e)$ is a primary expression of type t_2 . A function which takes no parameters is invoked without following its identifier by brackets. It will be an error if any of the actual parameters supplied to a function are incompatible with the formal parameters declared for the function.

<set construction>	'[' <element> [,<element>]*] '
--------------------	----------------------------------

Finally a primary expression may be a set construction. A set construction is written as a sequence of zero or more elements enclosed in brackets [] and separated by commas. The elements themselves are either expressions evaluating to single values or range expressions denoting a sequence of consecutive values. The type of a set construction is deduced by the compiler from the context in which it occurs. A set construction occurring on the right hand side of an assignment inherits the type of the variable to which it is being assigned. The following are all valid set constructions:

`[]`, `[1..9]`, `[z..j,9]`, `[a,b,c,]`, `['beyond','all','limit']`
`[]` denotes the empty set.

3.1.3 Unary expressions

A unary expression is formed by applying a unary operator to another unary or primary expression. The unary operators supported are `+`, `-`, `*`, `/`, `div`, `mod`, `and`, `or`, `not`, `round`, `sqrt`, `abs`, `byte2pixel`, `pixel2byte`, `succ`, `pred`, `iota`, `trans`, `addr`, `ln`, `ord`, `chr`, `sin`, `cos`, `tan`, and `@`.

Thus the following are valid unary expressions: `-1`, `+b`, `not true`, `sqrt abs x`, `sin theta`. In standard Pascal some of these operators are treated as functions. Syntactically this means that their arguments must be enclosed in brackets, as in `sin(theta)`. This usage is also recognised by the Glasgow Pascal Compiler.

The dyadic operators `+`, `-`, `*`, `/`, `div`, `mod`, `and` and `or` are all extended to unary context by the insertion of an implicit value under the operation. Thus just as `-a = 0-a` so too `/2 = 1/2`. For sets the notation `-s` means the complement of the set s . The implicit value inserted are given below.

type	operators	implicit value
number	<code>+</code> , <code>-</code>	0
string	<code>+</code>	"
set	<code>+</code> , <code>-</code>	empty set
number	<code>*</code> , <code>/</code> , <code>div</code> , <code>mod</code>	1
number	<code>max</code>	lowest representable number of the type
number	<code>min</code>	highest representable number of the type
boolean	<code>and</code>	true
boolean	<code>or</code>	false

A unary operator can be applied to an array argument and returns an array result. Similarly any user declared function over a scalar type can be applied to an array type and

Table 3.1: Unary operators

lhs	rhs	meaning
<unaryop>	'+'	+x = 0+x identity operator
	'-'	-x = 0-x, note: this is defined on integer, real and complex
	'*', '×'	*x=1*x identity operator
	'/'	/x=1.0/x note: this is defined on integer, real and complex
	'div', '÷'	div x = 1 div x
	'mod'	mod x = 1 mod x
	'and'	and x = true and x
	'or'	or x = false or x
	'not', '¬'	complements booleans
	'round'	rounds a real to the closest integer
	'sqrt', '√'	returns square root as a real number.
	'sin'	sine of its argument. Argument in radians. Result is real.
	'cos'	cosine of its argument. Argument in radians. Result is real.
	'tan'	tangent of its argument. Argument in radians. Result is real.
	'abs'	if x<0 then abs x = -x else abs x= x
	'ln'	log _e of its argument. Result is real.
	'ord'	argument scalar type, returns ordinal number of the argument.
	'chr'	converts an integer into a character.
	'succ'	argument scalar type, returns the next scalar in the type.
	'pred'	argument scalar type, returns the previous scalar in the type.
	'iota', 'ι'	iota i returns the ith current index
	'trans'	transposes a matrix or vector
	'pixel2byte'	convert pixel in range -1.0..1.0 to byte in range 0..255
	'byte2pixel'	convert a byte in range 0..255 to a pixel in the range -1.0..1.0
	'@', 'addr'	Given a variable, this returns an untyped pointer to the variable.

return an array. If f is a function or unary operator mapping from type r to type t then if x is an array of r , and a an array of t , then $a:=f(x)$ assigns an array of t such that $a[i]=f(x[i])$

<unary expression>	<unaryop> <unary expression> 'sizeof' '(' <type> ')' <operator reduction> <primary expression>
	'if' <expression> 'then' <expression> 'else' <expression>

sizeof

The construct `sizeof (t)` where t is a type, returns the number of bytes occupied by an instance of the type.

iota

The operation `iota i` returns the *i*th current implicit index¹.

Examples Thus given the definitions

```
var v1:array[1..3]of integer;
v2:array[0..4] of integer;
then the program fragment
v1:=iota 0;
v2:=iota 0 *2;
for i:=1 to 3 do write( v1[i]); writeln;
for i:=0 to 4 do write( v2[i]); writeln;
would produce the output
```

```
1 2 3
0 2 4 6 8
```

whilst given the definitions

```
m1:array[1..3,0..4] of integer;m2:array[0..4,1..3]of integer;
then the program fragment
m2:= iota 0 +2*iota 1;
writeln('m2:= iota 0 +2*iota 1 ');
for i:=0 to 4 do begin for j:=1 to 3 do write(m2[i,j]); writeln; end;
```

would produce the output

```
m2:= iota 0 +2*iota 1
2 4 6
3 5 7
4 6 8
5 7 9
6 8 10
```

The argument to `iota` must be an integer known at compile time within the range of implicit indices in the current context. The reserved word `ndx` is a synonym for `iota`.

perm A generalised permutation of the implicit indices is performed using the syntactic form:

```
perm[index-sel [, index-sel] * ]expression
```

The *index-sels* are integers known at compile time which specify a permutation on the implicit indices. Thus in *e* evaluated in context `perm[i,j,k]e`, then:

```
iota 0 = iota i, iota 1= iota j, iota 2= iota k
```

This is particularly useful in converting between different image formats. Hardware frame buffers typically represent images with the pixels in the red, green, blue, and alpha channels adjacent in memory. For image processing it is convenient to hold them in distinct planes. The `perm` operator provides a concise notation for translation between these formats:

¹See section 3.2.1.


```

type rowindex=0..479;
   colindex=0..639;
var channel=red.alpha;
   screen=array[rowindex,colindex,channel] of pixel;
   img=array[channel,colindex,rowindex] of pixel;
...
screen:=perm[2,0,1]img;

```

`trans` and `diag` provide shorthand notions for expressions in terms of `perm`. Thus in an assignment context of rank 2, `trans = perm[1,0]` and `diag = perm[0,0]`.

trans

The operator `trans` transposes a vector or matrix. It achieves this by cyclic rotation of the implicit indices. Thus if `trans e` is evaluated in a context with implicit indices

```

iota 0.. iota n
then the expression e is evaluated in a context with implicit indices
iota'0.. iota'n
where
iota'x = iota ((x+1) mod n+1)

```

It should be noted that transposition is generalised to arrays of rank greater than 2.

Examples Given the definitions used above in section 3.1.3, the program fragment:

```

m1:= (trans v1)*v2;
writeln('(trans v1)*v2');
for i:=1 to 3 do begin for j:=0 to 4 do write(m1[i,j]); writeln; end;

m2 := trans m1;
writeln('transpose 1..3,0..4 matrix');
for i:=0 to 4 do begin for j:=1 to 3 do write(m2[i,j]); writeln; end;
will produce the output:

```

```

(trans v1)*v2
0 2 4 6 8
0 4 8 12 16
0 6 12 18 24
transpose 1..3,0..4 matrix
0 0 0
2 4 6
4 8 12
6 12 18
8 16 24

```

3.1.4 Operator Reduction

Any dyadic operator can be converted to a monadic reduction operator by the functional `\`. Thus if `a` is an array, `\+a` denotes the sum over the array. More generally `\Φx` for some dyadic operator `Φ` means $x_0\Phi(x_1\Phi..(x_n\Phi t))$ where `t` is the implicit value given the operator and the type. Thus we can write `\+` for summation, `*` for nary product etc. The dot product of two vectors can thus be written as

```
x:= \+ y*x;
```

instead of

```
x:=0;
for i:=0 to n do x:= x+ y[i]*z[i];
```

A reduction operation takes an argument of rank r and returns an argument of rank $r-1$ except in the case where its argument is of rank 0, in which case it acts as the identity operation. Reduction is always performed along the last array dimension of its argument.

The operations of summation and product can be written either as the two functional forms $\backslash +$ and $\backslash *$ or as the prefix operators Σ (Unicode 2211) and Π (Unicode 220f).

<operator reduction>	'\ \backslash '<dyadic op> <multiplicative expression> ' Σ ' <multiplicative expression> ' Π ' <multiplicative expression>
<dyadic op>	<expop> <multop> <addop>

The reserved word `rdu` is available as a lexical alternative to \backslash , so $\backslash +$ is equivalent to `rdu+`.

3.1.5 Complex conversion

Complex numbers can be produced from reals using the function `cmplx`. `cmplx(re,im)` is the complex number with real part re , and imaginary part im .

The real and imaginary parts of a complex number can be obtained by the functions `re` and `im`. `re(c)` is the real part of the complex number c . `im(c)` is the imaginary part of the complex number c .

3.1.6 Conditional expressions

The conditional expression allows two different values to be returned dependent upon a boolean expression.

```
var a:array[0..63] of real;
...

a:=if a>0 then a else -a;

...
```

The `if` expression can be compiled in two ways:

1. Where the two arms of the `if` expression are parallelisable, the condition and both arms are evaluated and then merged under a boolean mask. Thus, the above assignment would be equivalent to:

```
a:= (a and (a>0)) or (not (a>0) and -a);
```

were the above legal Pascal².

2. If the code is not parallelisable it is translated as equivalent to a standard `if` statement. Thus, the previous example would be equivalent to:

```
for i:=0 to 63 do if a[i]>0 then a[i]:=a[i] else a[i]:=-a[i];
```

Expressions are non parallelisable if they include function calls.

²This compilation strategy requires that `true` is equivalent to `-1` and `false` to `0`. This is typically the representation of booleans returned by vector comparison instructions on SIMD instruction sets. In the Glasgow Pascal Compiler this representation is used generally and in consequence, `true<false`.

Table 3.2: Null elements for boolean masking

Type	Null Element
Numbers	0
Strings	empty string
Booleans	false

The dual compilation strategy allows the same linguistic construct to be used in recursive function definitions and parallel data selection.

Use of boolean mask vectors

In array programming many operations can be efficiently be expressed in terms of boolean mask vectors. Given the declarations:

```
const
  s:array[1..4] of string[8]='dog','fish','bee','beans';
  i:array[1..4] of integer=(1,2,3,4);
  r:array[1..4] of real=(0.5,1.0,2.0,4.0);
  b:array[1..4] of boolean=(false,true,false,true);
var
  c:array[1..4] of complex;
```

and if c is initialised to `cmplx(1,0.5)`, then the statements

```
write (b,i and b, r and b);
write(s:12, (s and b):12 );
write(c and b);
```

will output

false	true	false	true
0	2	0	4
0	1	0	4
dog	fish	bee	beans
	fish		beans
0j0	1j5e-1	0j0	1j5e-1

and operations using boolean arrays are particularly usefull in performing parallel selection operations on arrays. For numeric types, they commpile efficiently to SIMD code. Anding a value with boolean true leaves the value unchanged, anding with false returns a null element.

3.1.7 Factor

A factor is an expression that optionally performs exponentiation. Extended Pascal supports exponentiation either by integer exponents or by real exponents. A number x can be raised to an integral power y by using the construction $x \text{ pow } y$. A number can be raised to an arbitrary real power by the `**` operator. The result of `**` is always real valued.

<expop>	'pow' '**'
<factor>	<unary expression> [<expop> <unary expression>]

Table 3.3: Multiplicative operators

Operator	Left	Right	Result	Effect of $a \text{ op } b$
*, ×	integer	integer	integer	multiply
	string	integer	string	replicate, 'ab'*2='abab'
	real	real	real	multiply
	complex	complex	complex	multiply
/	integer	integer	real	division
	real	real	real	division
	complex	complex	complex	division
div, ÷	integer	integer	integer	division
mod	integer	integer	integer	remainder
and	boolean	boolean	boolean	logical and
shr	integer	integer	integer	shift a by b bits right
shl	integer	integer	integer	shift a by b bits left
in, ∈	t	set of t	boolean	true if a is member of b

3.1.8 Multiplicative expressions

Multiplicative expressions consist of factors linked by the multiplicative operators *, ×, /, div, ÷, mod, shr, shl and. The use of these operators is summarised in table 3.3.

<multop>	'*' '×' '/' 'div' '÷' 'shr' 'shl' 'and' 'mod'
<multiplicative expression>	<factor> [<multop> <factor>]* <factor>'in'<multiplicative expression>

3.1.9 Additive expressions

An additive expression allows multiplicative expressions to be combined using the addition operators +, -, or, +:, max, min, -: , >. The additive operations are summarised in table 3.4 .

<addop>	'+' '-' 'or' 'max' 'min' '+:' '-:'
---------	--

<additive expression>	<multiplicative expression> [<addop> <multiplicative expression>]*
<expression>	<additive expression> <relational operator> <expression>

Table 3.4: Addition operations

	Left	Right	Result	Effect of $a \text{ op } b$
+	integer	integer	integer	sum of a and b
	real	real	real	sum of a and b
	complex	complex	complex	sum of a and b
	set	set	set	union of a and b
	string	string	string	concatenate a with b 'ac'+ 'de'='acde'
-	integer	integer	integer	result of subtracting b from a
	real	real	real	result of subtracting b from a
	complex	complex	complex	result of subtracting b from a
	set	set	set	complement of b relative to a
+:	0..255	0..255	0..255	saturated + clipped to 0..255
	-128..127	-128..127	-128..127	saturated + clipped to -128..127
-:	0..255	0..255	0..255	saturated - clipped to 0..255
	-128..127	-128..127	-128..127	saturated - clipped to -128..127
min	integer	integer	integer	returns the lesser of the numbers
	real	real	real	returns the lesser of the numbers
max	integer	integer	integer	returns the greater of the numbers
	real	real	real	returns the greater of the numbers
or	boolean	boolean	boolean	logical or
><	set	set	set	symetric difference

Table 3.5: Relational operators

<	Less than
>	Greater than
<=	Less than or equal to
>=	Greater than or equal to
<>	Not equal to
=	Equal to
in	Tests set membership, right operand must be a set
is	Tests class membership, left operand an instance right operand a class type

3.1.10 Expressions

An expression can optionally involve the use of a relational operator to compare the results of two additive expressions. Relational operators always return boolean results and are listed in table 3.5.

3.1.11 Operator overloading

The dyadic operators can be extended to operate on new types by operator overloading. Figure 3.1 shows how arithmetic on the type `complex` required by Extended Pascal [16] is defined in Vector Pascal. Each operator is associated with a semantic function and if it is a non-relational operator, an identity element. The operator symbols must be drawn from the set of predefined Vector Pascal operators, and when expressions involving them are parsed, priorities are inherited from the predefined operators. The type signature of the operator is deduced from the type of the function³.

³Vector Pascal allows function results to be of any non-procedural type.

```

interface
  type
    Complex = record data : array [0..1] of real ;
    end ;

  var
    complexzero, complexone : complex;

  function real2cplx ( realpart :real ):complex ;
  function cplx ( realpart ,imag :real ):complex ;
  function complex_add ( A ,B :Complex ):complex ;
  function complex_conjugate ( A :Complex ):complex ;
  function complex_subtract ( A ,B :Complex ):complex ;
  function complex_multiply ( A ,B :Complex ):complex ;
  function complex_divide ( A ,B :Complex ):complex ;
  { Standard operators on complex numbers }
  { symbol function identity element }
  operator + = Complex_add , complexzero ;
  operator / = complex_divide , complexone ;
  operator * = complex_multiply , complexone ;
  operator - = complex_subtract , complexzero ;
  operator cast = real2cplx ;

```

Note that only the function headers are given here as this code comes from the interface part of the system unit. The function bodies and the initialisation of the variables `complexone` and `complexzero` are handled in the implementation part of the unit.

Example 3.1: Defining operations on complex numbers

<code><operator-declaration></code>	<code>'operator' 'cast' '=' <identifier></code> <code>'operator' <dyadicop> '=' <identifier>','<identifier></code> <code>'operator' <relational operator> '=' <identifier></code>
---	---

When parsing expressions, the compiler first tries to resolve operations in terms of the predefined operators of the language, taking into account the standard mechanisms allowing operators to work on arrays. Only if these fail does it search for an overloaded operator whose type signature matches the context.

In the example in figure 3.1, complex numbers are defined to be records containing an array of reals, rather than simply as an array of reals. Had they been so defined, the operators `+`, `*`, `-`, `/` on reals would have masked the corresponding operators on complex numbers.

The provision of an identity element for complex addition and subtraction ensures that unary minus, as in $-x$ for x :complex, is well defined, and correspondingly that unary `/` denotes complex reciprocal. Overloaded operators can be used in array maps and array reductions.

Implicit casts

The Vector Pascal language already contains a number of implicit type conversions that are context determined. An example is the promotion of integers to reals in the context of arithmetic expressions. The set of implicit casts can be added to by declaring an operator to be a cast as is shown in the line:

```
operator cast = real2cplx ;
```

```

{:tests vector product of integer vectors }
program conf551;
const
  a:array[0..3] of integer=(1,1,2,3);
  b:array[0..3] of integer=(1,2,3,4);
var i:integer;
begin
  i:=a.b;
  if i=21 then
    writeln('PASS integer vector product allowed')
  else
    writeln('FAIL integer vector product i=',i)
end.

```

Example 3.2: Example of the inner product operation

```

{:tests vector product of string and integer }
program conf550;
const roman:array[0..4] of string[3]=('C','L','X','V','I');
      num: array[0..4] of integer =(1,1,2,0,3);
var s:string[80];
begin
  s:=num.roman;
  if s='CLXXIII' then
    writeln('PASS string integer vector product allowed')
  else
    writeln('FAIL CONF550 string integer vector product s=',s)
end.

```

Example 3.3: Using vector product to format roman numerals

Given an implicit cast from type $t_0 \rightarrow t_1$, the function associated with the implicit cast is then called on the result of any expression $e : t_0$ whose expression context requires it to be of type t_1 .

3.1.12 Vector inner product

The inner product of two vectors is defined as:

$$a.b = \sum_i a_i \times b_i$$

or in Vector Pascal notation: $a.b = \setminus + a*b$. Vector Pascal supports this inner product operation on any pair of vectors with the following properties:

1. The lengths of the vectors must be the same.
2. The types of the vectors must be such that they support the operators $+$ and $*$.

Inner product can obviously be used on numeric vectors as shown in Example 3.2 but it can also be used with other types for which $+$ and $*$ are defined, as shown in Example 3.3.

The inner product operation is of higher priority than any other. Its arguments must be arrays.

3.1.13 Matrix to Vector Product

Matrix to vector product can be used to carry out generalised linear geometry transforms. We can do this in Vector Pascal if a two dimensional array is used to multiply a one dimensional array, using the dot product operator. If M is a two dimensional array and v a vector, $M.v$ produces the transformed vector.

VECTOR

The program `matvmult` shown in Example 3.4, shows the repeated application of a rotation and translation matrix to the unit x vector. When the matrix

$$\begin{array}{cccc} \frac{1}{\sqrt{2}} & \frac{-1}{\sqrt{2}} & 0 & 0 \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 & 0 \\ 0 & 0 & 1 & 0.2 \\ 0 & 0 & 0 & 1 \end{array}$$

is applied to a vector of the form $[x, y, z, 1]$, it rotates it by 45° and moves it up by 0.2.

Data-flow Hazards

Note that in Example 3.4, one can not simply write `v1:=M.v1`, instead one has to write:

```
v2:=M.v1;
v1:=v2;
```

since the vector `v1` might be changing whilst it was being read. Had the compiler been encountered this statement it would have generated the error messages:

```
compilation failed
17 : Error  assignment invalid
17 : Error  in primary expression started by m
17 : Error  attempting to reduce rank of variable
17 : Error  data hazard found. Destination v1 is used with
          an index permutation on right hand side of := which
          can cause it to be corrupted.
          You can get round this by assigning to a temporary
          array instead and then assigning the temporary to
          destination v1
```

A check for data-flow hazards is applied to all array assignment statements. If array expressions could all be evaluated in parallel, then there would be no hazards. The problem arises because only simple array expressions can be evaluated entirely in parallel. In other cases the array assignment has to be broken down by the compiler into a sequence of steps. This gives rise to the danger that an array location may be altered by an early step prior to it being used a source of data by a subsequent step.

In most cases there will be no problem even where the destination vector appears on the right hand side of an assignment. Thus:

```
M:=M+v;
```

for some matrix M and vector v , is ok, since here each element of M depends only on its own prior value. However for `v1:=M.v1`, we have the equations

$$v1_0 = \sum_{j=0}^3 M_{0j}v1_j \quad (3.1)$$

$$v1_1 = \sum_{j=0}^3 M_{1j}v1_j \quad (3.2)$$

In which ever order the code for these equations is evaluated, either $v1_0$ or $v1_1$ will be altered before it is used in the other equation.


```

program matvmult;
type vec=array[0..3] of real;
      mat=array[0..3] of vec;
const
  rr2= 0.7071067 ;           { 1/sqrt(2) }
  M:mat=(( rr2,-rr2,0.0,0.0) , { 45degree spiral matrix }
        (rr2,rr2,0.0,0.0),
        (0.0,0.0,1.0,0.2),
        (0.0,0.0,0.0,1.0));
  v:vec=(1.0,0.0,0.0,1.0);
var v1,v2:vec; i:integer;
begin
  write (M,v);
  v1:=v;
  (* perform 8 45degree rotations *)
  for i:=1 to 8 do begin
    v2:=M.v1;
    v1:=v2;
    write(v1);
  end;
end.

```

produces as output

0.70711	-0.70711	0.00000	0.00000
0.70711	0.70711	0.00000	0.00000
0.00000	0.00000	1.00000	0.20000
0.00000	0.00000	0.00000	1.00000
1.00000	0.00000	0.00000	1.00000
0.70711	0.70711	0.20000	1.00000
0.00000	1.00000	0.40000	1.00000
-0.70711	0.70711	0.60000	1.00000
-1.00000	-0.00000	0.80000	1.00000
-0.70711	-0.70711	1.00000	1.00000
-0.00000	-1.00000	1.20000	1.00000
0.70711	-0.70711	1.40000	1.00000
1.00000	-0.00000	1.60000	1.00000

Example 3.4: Using a spiral rotation matrix to operate on the unit x vector.

```

program matmmult;
const
  A:array[1..2,1..3] of integer=((3,1,2),
                                (2,1,3));
  B:array[1..3,1..2] of integer=((1,2),
                                (3,1),
                                (2,3));
var C:array[1..2,1..2] of integer;
begin
  C:=A.B;
  writeln(C);
end.

```

Produces output

```

      10      13
      11      14

```

Example 3.5: Matrix by matrix multiplication.

3.1.14 Matrix to Matrix multiplication

VECTOR

The dot operator can be used between matrices to perform matrix multiplication as illustrated in Example 3.5. This applies the standard equation for matrix multiplication:

$$c_{ik} = \sum_{s=1}^p a_{is}b_{sk} \quad (3.3)$$

where A is of order $(m \times p)$ and B is of order $(p \times n)$ to give a resulting matrix C of order $(m \times n)$.

3.2 Statements

<statement>	<variable>:=<expression> <procedure statement> <empty statement> 'goto' <label>; 'exit'['(<expression>')'] 'begin' <statement>[;<statement>]*'end' 'if' <expression>'then' <statement>['else' <statement>] <case statement> 'for' <variable>:= <expression> 'to' <expression> 'do' <statement> 'for' <variable>:= <expression> 'downto' <expression> 'do' <statement> 'for' <variable> 'in' <expression> 'do' <statement> 'repeat' <statement> 'until' <expression> 'with' <record variable> 'do' <statement> <io statement> 'while' <expression> 'do' <statement>
-------------	--

3.2.1 Assignment

An assignment replaces the current value of a variable by a new value specified by an expression. The assignment operator is :=. Standard Pascal allows assignment of whole

arrays. Vector Pascal extends this to allow consistent use of mixed rank expressions on the right hand side of an assignment. Given

```
r0:real; r1:array[0..7] of real;
```

```
r2:array[0..7,0..7] of real
```

then we can write

1. `r1:= r2[3];` { supported in standard Pascal }
2. `r1:= /2;` { assign 0.5 to each element of r1 }
3. `r2:= r1*3;` { assign 1.5 to every element of r2}
4. `r1:= \+ r2;` { r1 gets the totals along the rows of r2}
5. `r1:= r1+r2[1];`{ r1 gets the corresponding elements of row 1 of r2 added to it}

The assignment of arrays is a generalisation of what standard Pascal allows. Consider the first examples above, they are equivalent to:

1. `for i:=0 to 7 do r1[i]:=r2[3,i];`
2. `for i:=0 to 7 do r1[i]:=/2;`
3. `for i:=0 to 7 do`
`for j:=0 to 7 do r2[i,j]:=r1[j]*3;`
4. `for i:=0 to 7 do`
`begin`
`t:=0;`
`for j:=7 downto 0 do t:=r2[i,j]+t;`
`r1[i]:=t;`
`end;`
5. `for i:=0 to 7 do r1[i]:=r1[i]+r2[1,i];`

In other words the compiler has to generate an implicit loop over the elements of the array being assigned to and over the elements of the array acting as the data-source. In the above `i, j, t` are assumed to be temporary variables not referred to anywhere else in the program. The loop variables are called implicit indices and may be accessed using `iota`.

The variable on the left hand side of an assignment defines an array context within which expressions on the right hand side are evaluated. Each array context has a rank given by the number of dimensions of the array on the left hand side. A scalar variable has rank 0. Variables occurring in expressions with an array context of rank r must have r or fewer dimensions. The n bounds of any n dimensional array variable, with $n \leq r$ occurring within an expression evaluated in an array context of rank r must match with the rightmost n bounds of the array on the left hand side of the assignment statement.

Where a variable is of lower rank than its array context, the variable is replicated to fill the array context. This is shown in examples 2 and 3 above. Because the rank of any assignment is constrained by the variable on the left hand side, no temporary arrays, other than machine registers, need be allocated to store the intermediate array results of expressions.

The compiler will attempt to vectorise 1 array assignments provided that the underlying hardware supports vectorisation. If the code has been compiled with the `-cores` directive the compiler will attempt to parallelise the evaluation of 2 dimensional array assignments across multiple cores.

3.2.2 Procedure statement

A procedure statement executes a named procedure. A procedure statement may, in the case where the named procedure has formal parameters, contain a list of actual parameters. These are substituted in place of the formal parameters contained in the declaration. Parameters may be value parameters or variable parameters.

Semantically the effect of a value parameter is that a copy is taken of the actual parameter and this copy substituted into the body of the procedure. Value parameters may be structured values such as records and arrays. For scalar values, expressions may be passed as actual parameters. Array expressions are not currently allowed as actual parameters.

A variable parameter is passed by reference, and any alteration of the formal parameter induces a corresponding change in the actual parameter. Actual variable parameters must be variables.

<code><parameter></code>	<code><variable></code> <code><expression></code>	for formal parameters declared as var for other formal parameters
<code><procedure statement></code>	<code><identifier></code> <code><identifier> '(' <parameter> ['<parameter>']* ')'</code>	

Examples

1. `printlist;`
2. `compare(avec,bvec,result);`

3.2.3 Goto statement

A goto statement transfers control to a labelled statement. The destination label must be declared in a label declaration. It is illegal to jump into or out of a procedure.

Example `goto 99;`

3.2.4 Exit Statement

An exit statement transfers control to the calling point of the current procedure or function. If the exit statement is within a function then the exit statement can have a parameter: an expression whose value is returned from the function.

Examples

1. `exit;`
2. `exit(5);`

3.2.5 Compound statement

A list of statements separated by semicolons may be grouped into a compound statement by bracketing them with `begin` and `end`.

Example `begin a:=x*3; b:=sqrt a end;`

3.2.6 If statement

The basic control flow construct is the if statement. If the boolean expression between `if` and `then` is true then the statement following `then` is followed. If it is false and an `else` part is present, the statement following `else` is executed.

3.2.7 Case statement

The case statement specifies an expression which is evaluated and which must be of integral or ordinal type. Dependent upon the value of the expression control transfers to the statement labelled by the matching constant.

<case statement>	'case'<expression>'of'<case actions>'end'
<case actions>	<case list> <case list> 'else' <statement> <case list> 'otherwise' <statement>
<case list>	<case list element>[';']<case list element.>*
<case list element>	<case label>[',' <case label>]':<statement>
<case label>	<constant> <constant> '..' <constant>

Examples

```

      case i of
1:s:=abs s;
2:s:= sqrt s;
3: s:=0
end
      case c of
'a':write('A');
'b','B':write('B');
'A','C'..'Z','c'..'z':write(' ');
end

```

3.2.8 With statement

Within the component statement of the with statement the fields of the record variable can be referred to without prefixing them by the name of the record variable. The effect is to import the component statement into the scope defined by the record variable declaration so that the field-names appear as simple variable names.

Example

```

var s:record x,y:real end;
begin
with s do begin x:=0;y:=1 end ;
end

```

3.2.9 For statement

A for statement executes its component statement repeatedly under the control of an iteration variable. The iteration variable must be of an integral or ordinal type. The variable is either set to count up through a range or down through a range.

```

for i:= e1 to e2 do s
is equivalent to
i:=e1; temp:=e2;while i<=temp do s;
whilst
for i:= e1 downto e2 do s
is equivalent to
i:=e1; temp:=e2;while i>= temp do s;

```

3.2.10 Vectorised For statements

The default is for all for loops to be executed sequentially, but if either multi-core code is selected or the -fastforloop option is supplied on the commandline and the underlying hardware supports vectorvectorisefor loops. That is to say if the loop is a simple assignment, contains no function calls, and there are no detectable loop dependencies, the loop will be

transformed into a loop with fewer iterations that works on several words of data at once. Thus if the programme had been compiled

3.2.11 Parallel For statements

On a multi-core machine it is possible to execute a for statement in parallel on the different cores. To do this you must precede the for statement by a comment containing the directive `$par` thus:

```
{$par}
    for j:=1 to 100 do
        for i:= 1 to 100 do
            d[j,i]:=a[i]*b[j];
```

In this case the outer loop is potentially run in parallel across the cores. To take advantage of this you must inform the compiler on the command line how many cores it is to compile the program for. For example

```
vpc myprog -cpuAVX32 -cores12
```

would compile `myprog` for a computer running the AVX instructions, to generate 32 bit code, running on 12 cores.

If the loop is run on many cores the value of the loop iterator variables and the iterator variables of any nested loops are undefined on exit from the outermost loop. Thus in the example above the values of `i`, `j` are undefined on exit from the parallel code.

The parallel for statements must not use the word `downto`, ie they should notionally be upward counting. But if the loop is run on many cores the order in which the instances of the loop body are executed are, in fact, undefined. It is the responsibility of the programmer not to use code in a parallel loop that is in any way order dependent.

3.2.12 While statement

A while statement executes its component statement whilst its boolean expression is true. The statement

```
while e do s
is equivalent to
10:  if not e then goto 99; s; goto 10; 99:
```

3.2.13 Repeat statement

A repeat statement executes its component statement at least once, and then continues to execute the component statement until its component expression becomes true.

```
repeat s until e
is equivalent to
10:  s;if e then goto 99; goto 10;99:
```

3.3 Input Output

<io statement>	'writeln' [<outparamlist>] 'write' <outparamlist> 'readln' [<inparamlist>] 'read' <inparamlist>
<outparamlist>	'(<outparam>[','<outparam>]*)'
<outparam>	<expression>[':'<expression>] [':'<expression>]
<inparamlist>	'(<variable>[',<variable>]*)'

Input and output are supported from and to the console and also from and to files.

3.3.1 Input

The basic form of input is the `read` statement. This takes a list of parameters the first of which may optionally be a file variable. If this file variable is present it is the input file. In the absence of a leading file variable the input file is the standard input stream. The parameters take the form of variables into which appropriate translations of textual representations of values in the file are read. The statement

```
read(a,b,c)
```

where a,b,c are non file parameters is exactly equivalent to the sequence of statements

```
read(a); read(b); read(c)
```

The `readln` statement has the same effect as the `read` statement but finishes by reading a new line from the input file. The representation of the new line is operating system dependent. The statement

```
readln(a,b,c)
```

where a,b,c are non file parameters is thus exactly equivalent to the sequence of statements

```
read(a); read(b); read(c); readln;
```

Allowed typed for `read` statements are: integers, reals, strings and enumerated types.

3.3.2 Output

The basic form of output is the `write` statement. This takes a list of parameters the first of which may optionally be a file variable. If this file variable is present it is the output file. In the absence of a leading file variable the output file is the console. The parameters take the form of expressions whose values whose textual representations are written to the output file. The statement

```
write(a,b,c)
```

where a,b,c are non file parameters is exactly equivalent to the sequence of statements

```
write(a); write(b); write(c)
```

The `writeln` statement has the same effect as the `write` statement but finishes by writing a new line to the output file. The representation of the new line is operating system dependent. The statement

```
writeln(a,b,c)
```

where a,b,c are non file parameters is thus exactly equivalent to the sequence of statements

```
write(a); write(b); write(c); writeln;
```

Allowed types for `write` statements are integers, reals, strings and enumerated types.

Parameter formatting

A non file parameter can be followed by up to two integer expressions prefixed by colons which specify the field widths to be used in the output. The `write` parameters can thus have

the following forms:

e e:m e:m:n

1. If *e* is an integral type its decimal expansion will be written preceded by sufficient blanks to ensure that the total textual field width produced is not less than *m*.
2. If *e* is a real its decimal expansion will be written preceded by sufficient blanks to ensure that the total textual field width produced is not less than *m*. If *n* is present the total number of digits after the decimal point will be *n*. If *n* is omitted then the number will be written out in exponent and mantissa form with 6 digits after the decimal point
3. If *e* is boolean the strings 'true' or 'false' will be written into a field of width not less than *m*.
4. If *e* If the value of *e* is a string-type value with a length of *n*, the default value of *m* shall be *n*. The representation shall consist of

```

if m > n,
    (m - n) spaces,
if n > 0,
    the first through n-th characters of the value of e in that order.
if 1 <= m <= n,
    the first through m-th characters in that order.
if m = 0,
    no characters.

```


Chapter 4

Programs, Units and Libraries

Vector Pascal supports the popular system of separate compilation units found in Turbo Pascal. A compilation unit can be either a program, a unit or a library.

<program>	'program' <identifier>;' [<uses>;'] <block>.'
<invocation>	<unitid>[' (' <type identifier>['; <type identifier>']*)']
<unitid>	<identifier>['.' 'apu' <identifier> ' [' <intconst>']]
<uses>	'uses' <invocation>['; <invocation>']*
<block>	[<decls>;]* 'begin' <statement>['; <statement>']* 'end'
<decls>	'const' <constant declaration>['; <constant declaration>']* 'type' <type definition>['; <type definition>']* 'label' <label>['; <label>] <procedure declaration> 'var' <variable declaration>['; <variable declaration>]
<unit>	<unit header> <unit body>
<unit body>	'interface' [<uses>] [<decls>] 'implementation' <block> '.' 'interface' [<uses>] [<decls>] 'in' <invocation> ';'
<unit header>	<unit type> <identifier> 'unit' <identifier> '(' <type identifier> [';' <type identifier>]* ')'
<unit type>	'unit' 'library'

An executable compilation unit must be declared as a program. The program can use several other compilation units all of which must be either units or libraries. The units or libraries that it directly uses are specified by a list of identifiers in an optional use list at the start of the program. A unit or library has two declaration portions and an executable block.

4.1 The export of identifiers from units

The first declaration portion is the interface part and is preceded by the reserved word `interface`.

The definitions in the interface section of unit files constitute a sequence of enclosing scopes, such that successive units in the with list ever more closely contain the program itself. Thus when resolving an identifier, if the identifier can not be resolved within the program scope, the declaration of the identifier within the interface section of the rightmost unit in the uses list is taken as the defining occurrence. It follows that rightmost occurrence of an identifier definition within the interface parts of units on the uses list overrides all occurrences in interface parts of units to its left in the uses list.

```

unit genericsort(t);
interface
type
    dataarray ( n,m :integer )=array [n..m] of t;
procedure sort ( var a :dataarray ); (see Figure 4.2)

implementation

procedure sort ( var a :dataarray ); (see Figure 4.2)
begin
end .

```

Example 4.1: A polymorphic sorting unit.

The implementation part of a unit consists of declarations, preceded by the reserved word `implementation` that are private to the unit with the exception that a function or procedure declared in an interface context can omit the procedure body, provided that the function or procedure is redeclared in the implementation part of the unit. In that case the function or procedure heading given in the interface part is taken to refer to the function or procedure of the same name whose body is declared in the implementation part. The function or procedure headings sharing the same name in the interface and implementation parts must correspond with respect to parameter types, parameter order and, in the case of functions, with respect to return types.

A unit may itself contain a use list, which is treated in the same way as the use lists of a program. That is to say, the use list of a unit makes accessible identifiers declared within the interface parts of the units named within the use list to the unit itself.

4.1.1 The export of Operators from units

A unit can declare a type and export operators for that type.

4.2 Unit parameterisation and generic functions

Standard Pascal provides es some limited support for polymorphism in its `read` and `write` functions. Vector Pascal allows the writing of polymorphic functions and procedures through the use of parameteric units.

A unit header can include an optional parameter list. The parameters identifiers which are interpreted as type names. These can be used to declare polymorphic procedures and functions, parameterised by these type names. This is shown in figure 4.1.

4.3 The invocation of programs and units

Programs and units contain an executable block. The rules for the execution of these are as follows:

1. When a program is invoked by the operating system, the units or libraries in its use list are invoked first followed by the executable block of the program itself.
2. When a unit or library is invoked, the units or libraries in its use list are invoked first followed by the executable block of the unit or library itself.

```

procedure sort ( var a :dataarray );
var
  Let  $i, j \in \text{integer}$ ;
  Let  $temp \in t$ ;
begin
  for  $i \leftarrow a.n$  to  $a.m - 1$  do
    for  $j \leftarrow a.n$  to  $a.m - 1$  do
      if  $a_j > a_{j+1}$  then begin begin
         $temp \leftarrow a_j$ ;
         $a_j \leftarrow a_{j+1}$ ;
         $a_{j+1} \leftarrow temp$ ;
      end ;
    end ;
end ;

```

Example 4.2: procedure sort

3. The order of invocation of the units or libraries in a use list is left to right with the exception provided by rule 4.
4. No unit or library may be invoked more than once.

Note that rule 4 implies that a unit x to the right of a unit y within a use list, may be invoked before the unit y , if the unit y or some other unit to y 's left names x in its use list.

Note that the executable part of a library will only be invoked if the library in the context of a Vector Pascal program. If the library is linked to a main program in some other language, then the library and any units that it uses will not be invoked. Care should thus be taken to ensure that Vector Pascal libraries to be called from main programs written in other languages do not depend upon initialisation code contained within the executable blocks of units.

4.4 The compilation of programs and units.

When the compiler processes the use list of a unit or a program then, from left to right, for each identifier in the use list it attempts to find an already compiled unit whose filename prefix is equal to the identifier. If such a file exists, it then looks for a source file whose filename prefix is equal to the identifier, and whose suffix is `.pas`. If such a file exists and is older than the already compiled file, the already compiled unit, the compiler loads the definitions contained in the pre-compiled unit. If such a file exists and is newer than the pre-compiled unit, then the compiler attempts to re-compile the unit source file. If this re-compilation proceeds without the detection of any errors the compiler loads the definitions of the newly compiled unit. The definitions in a unit are saved to a file with the suffix `.mpu`, and prefix given by the unit name. The compiler also generates an assembler file for each unit compiled.

4.5 Instantiation of parametric units

Instantiation of a parametric unit refers to the process by which the unbound type variables introduced in the parameter list of the unit are bound to actual types. In Vector Pascal all instantiation of parametric units and all type polymorphism are resolved at compile time. Two mechanisms are provided by which a parametric unit may be instantiated.

4.5.1 Direct instantiation

If a generic unit is invoked in the use list of a program or unit, then the unit name must be followed by a list of type identifiers. Thus given the generic sort unit in figure 4.1, one could instantiate it to sort arrays of reals by writing

```
uses genericsort(real);
```

at the head of a program. Following this header, the procedure *sort* would be declared as operating on arrays of reals.

4.5.2 Indirect instantiation

A named unit file can indirectly instantiate a generic unit where its unit body uses the syntax

```
'interface' <uses><decls> 'in' <invocation> ';'
```

For example

```
unit intsort ;
interface
  in genericsort (integer);
```

would create a named unit to sort integers. The naming of the parametric units allows more than one instance of a given parametric unit to be used in a program. The generic sort unit could be used to provide both integer and real sorting procedures. The different variants of the procedures would be distinguished by using fully qualified names - e.g., *intsort.sort*.

4.6 Unit Pmats :Matrices on the heap

The matrix operations described so far all operate on array variables. If you want to get them to work with matrices on the heap you have to explicitly dereference the pointer to the array.

```
Type mymat=array[1..3,1..3] of double;
var a,c,d:mymat;b:^mymat;
begin
  new(b);
  ...
  a:= c.d;
  a:= b^.c;
```

is valid since the pointer *b* is explicitly dereferenced before using the *.* operator.

But

```
a:=b.c;
```

would generate a type error since no operator *.* exists that takes an array and a pointer to an array as arguments.

The compiler expands the statement

```
a:= b^.c;
```

in place as:

```

for i:=1 to 3 do
  for j:=1 to 3 do
    begin
      temp:=0.0;
      for k:= 1 to 3 do
        temp:= temp + b^[i,k]*c[k,j];
      a[i,j]:=temp
    end;
  end;
end;

```

This is just an example of the general approach taken by the code generation. All assignment statements for which the left hand side is an array value are similarly expanded in place into for loops. Depending on the compiler flags and the target CPU, these loops may then be automatically vectorised or parallelised to use multi-cores or SIMD instructions. Note that only a few scalar temporaries are used in this sort of expression evaluation, and these scalars can often be allocated as registers by the compiler.

The approach of expanding in situ is the obvious approach for any language that supports statically declared array types whose storage may be allocated either in the data segment or the stack segment. It avoids having to dynamically allocate heap array temporaries whilst evaluating complex expressions. Such heap allocation would have the disadvantages of

- Increasing the working set of data used by the code thus degrading cache performance.
- Involving additional computational load in heap storage allocation and deallocation.

For large matrix multiplication these advantages of in situ expansion do not apply. The order or access to the second array, *c* in the example above, has the row index varying most rapidly. If the array is large, then access to values $b[i,k], c[k,j]$ will cause perhaps 8 adjacent values from each to be loaded into the cache. The cache will then contain $b[i, k..k+7], c[k, j..j+7]$. But the next iteration wants $b[i, k+1], c[k+1, j]$ which will result in a cache hit for *b* and a probable miss for *c*. The organisation of the data also inhibits the compiler from using SIMD instructions.

To avoid this it is more efficient to call a matrix multiply function that returns a new matrix on the heap. An example function might be:

```

function fmatprod(a,b:pmatrix):pmatrix;
var p,c:pmatrix;i,j:integer;
begin
  p:=newmatrix(a^.rows,b^.cols);
  c:=newmatrix(b^.cols,b^.rows);
  c^:= trans b^;
  {$par} {pragma advising compiler to parallelise loop }
  for i:= 1 to a^.rows do
    for j:= 1 to b^.cols do
      p^[i,j]:= \+( a^[i] * c^[j] );
    dispose(c);
  fmatprod:=p;
end;

```

The type *pmatrix* is assumed to be a pointer to a heap matrix. This function allocates two new matrices on the heap, *p* to hold the final result and *c* to hold a temporary transposed copy of matrix *b*. Since this is transposed we can now invoke the built in vector reduction + to compute the inner product of the rows. Since the data is now organised so that sequential accesses are adjacent, both cache use improves and SIMD instructions can be generated. For large matrices the gains from evaluation this way will exceed the overheads

of heap allocation. If you are doing a lot of large matrix multiplies this way, it is advisable to enable automatic garbage collection using the `-BOEHM` compile time flag.

There are two library units `pmats`, `pvecs` now distributed with the compiler that work using the approach shown above. These are generic units which have to be parameterised with the value type you want to use in your matrices. So a program header

```
Uses pmats(double);
```

will instantiate a type `pmatrix` representing pointers to double precision matrices.

The units also extend the operators `+` `-` `*` `/` `.` to operate on the `pmatrix` type.

The function

```
function newmatrix( rows,cols:integer):pmatrix;
```

is provided to create matrices on the heap. The function

```
function transpose(a:pmatrix):pmatrix;
```

creates a transposed copy of the matrix pointed to by `a` on the heap.

The operators `+` `-` `*` `/` `.` may be used on values of type `pmatrix` without any pointer dereference. The operators `+` `-` `*` `/` can also be used between matrices and scalars so the following sequence is valid:

```
var a,b,c:pmatrix;
begin
  a:=newmatrix(4,4);
  a^:=1.0;
  a^[2]:=8.0;
  b:=transpose(a);
  c:=a * 7;
  b:= (a.b) -c;
```

4.7 Unit `invertgauss` - matrix inversions

This is a generic matrix inversion unit designed to maximise the number of adjacent elements to be extracted from the array, to allow SIMD optimisations. Note that this library is contributed by a different author to the `pmats` unit and it does not use the same generic matrix type.

The inversion of any matrix for which its inversion exists is the transpose of the adjunct of the matrix, divided by its determinant.

The adjunct of the matrix is the matrix found by replacing each element by its cofactor.

No solution exists if the determinant of the original matrix is 0 (divide by zero error).

4.7.1 Interface

```
type      intarray (n:integer) = array[0..N] of integer;
```

```
type      matrixNxN (n,m:integer)= array[0..N,0..M] of datum;
```

```
PROCEDURE invertMatrix (var a : matrixNxN);Find the inverse: overwrites a.
```

PROCEDURE invertTransposeMatrix (var a : matrixNxN) ; Find the transpose of the inverse: over writes a.

PROCEDURE matmul (var b,c,a : matrixNxN) ; Premultiply a matrix b with the transpose of second matrix, c. $a = b \times c^T$

PROCEDURE solve (var a,b,c : matrixNxN) ; Find c = a solve b

4.8 The System Unit

All programs and units include by default the unit system.pas as an implicit member of their with list. This contains declarations of private run time routines needed by Vector Pascal and also the following user accessible routines.

function abs Return absolute value of a real or integer.

function alias (array section) This returns a pointer to an array with the same type and occupying the same memory cells as the array section passed in.

procedure append (var f:file) ; This opens a file in append mode.

pure function ArcCos (x:Real):Real; **The inverse function of cos.** Calculates (approximates) the angle $\theta \in [0..\pi]$, such that $\cos \theta = \text{cosVal}$. Returns $\arccos(\text{cosVal})$ if $\text{cosVal} \in [-1,1]$. Returns the error code -5 otherwise.

pure function ArcSin (cosVal : real) : real; **The inverse function of sin.** Calculates (approximates) the angle $\theta \in [-\pi/2..\pi/2]$, such that $\sin \theta = \text{sinVal}$. Returns $\arcsin(\text{sinVal})$ if $\text{sinVal} \in [-1,1]$. Returns the error code -5 otherwise.

pure function arcTan(x:Real):Real;

procedure assign (var f:file; var fname:string) ; Associates a file name with a file. It does not open the file.

procedure blockread (var f:file; var buf; count:integer; var resultcount:integer) ; Tries to read count bytes from the file into the buffer. Resultcount contains the number actually read.

procedure blockwrite (var f:file; var buf; count:integer; var resultcount:integer) ; Write count bytes from the buffer. Resultcount gives the number actually read.

procedure chdir (path:pchar) ; Has the effect of executing cd on command line.

function chr (i:integer):char Converts an integer to the corresponding Unicode character.

procedure close (var f:file); Closes a file.

procedure closedir (d:pdir) ; external; Pascal declaration for the C runtime library function.

pure function cmplx (realpart, imag:real):complex; Function to build complex numbers.

function `complex_2_string (A:Complex):string`; Converts a complex number to a printable form.

procedure `delay (DTime: integer)`; Wait for DTime milliseconds.

function `eof(var f:file):boolean`; True if we are at the end of file f.

procedure `erase(var f:file)`; Delete file f.

function `eoln(var f:file):boolean`; True if at the end of a line.

function `exp(d:real):real`; Return e^x

function `filesize(var f: fileptr):integer`; Return number of bytes in a file.

function `filepos(var f:fileptr):integer`; Return current position in a file.

procedure `fillchar(var x;count :integer; value:integer)`; The function copies value into the first count characters of buffer x, it is useful for intializing a section of memory to some value.

pure function `floor(a:double):integer`; if a <0.0 then floor returns - trunc(0.0-a)-1 otherwisee it returns trunc(a)

pure function `frac(x:real):real`; Return fractional part of floating point value.

procedure `freemem(var p:pointer; num:integer)`; Free num bytes of heap store. Called by `dispose`.

procedure `getmem(var p:pointer; num:integer)`; Allocate num bytes of heap. Called by `new`.

procedure `gettime(var hour,min,sec,hundredth:integer)`; Return time of day.

procedure `halt(errornum:integer)`; Stop program execution.

pure function `im(c:complex):real`; Return the imaginary part of a complex number.

procedure `inc(var i:integer)`; Increments i.

pure function `int(r:real):real`; Return the integer part of r as a real.

function `ioresult:integer`; Returns a code indicating if the previous file operation completed ok. Zero if no error occurred.

function `isdir(path:pchar):boolean`; Return true if the null terminated string is a directory.

function `length(var s:string):integer`; Returns the length of s.

procedure `move(var source;var dest; len:integer)`; Copy len bytes from source to dest.

pure function `odd(i:integer):boolean`; True if i is odd.

function `opendir(path :pchar):pdir`; Posix function The `opendir()` function opens a directory stream corresponding to the directory name, and returns a pointer to the directory stream. The stream is positioned at the first entry in the directory.

procedure `page(var t:text)`; Generates a page throw in the file of char t.

function `paramcount:integer`; Number of parameters with which program was called

function paramstr(i:integer):textline; Retrieve parameters with which program was called.

procedure pascalexit(code:integer); Terminate the program with code.

function random:integer; Returns a random integer.

procedure randomize; Assign a new time dependent seed to the random number generator.

pure function re(c:complex):real; Return the real part of a complex number.

function readdir(d:pdir):pdirent; The Posix readdir() function returns a pointer to a dirent structure representing the next directory entry in the directory stream pointed to by dirp. It returns Nil on reaching the end of the directory stream or if an error occurred.

procedure reset(var f:file); Open a file for reading.

procedure rewrite(var f :file); Open a file for writing.

function secs:double; Time in 1/100 seconds since program started.

function seek(var f:fileptr;pos,mode:integer):integer; Seek sets the file-pointer for file F to record Nr. Count. The first record in a file has Count=0. F can be any file type, except Text.

function StrPas(Src: PChar): textline; Convert a C style null terminated string to a Pascal one.

function strlen(s:pchar):integer; Return the length of a C style null terminated string

pure function sqr(x:double):double; Squares the number. It is usually more efficient to do x*x.

function substring(s:string;i,j:integer):string; Creates a string made up of s[i..j].

function trunc(r:real):integer; Truncates a real to an integer.

procedure unicodestring2ascii(s:string;var asciibuffer); This converts a Pascal string which will be in Unicode to a string of 8 bit characters in asciibuffer. It does *not* perform conversion to UTF-8 it simply copies over the bottom 7 bits of each unicode character, so it will only work if the original string contains only characters with an ASCII equivalent.

procedure Val(S:string ; var V; var Code: integer); Val converts the value represented in the string S to a numerical value and stores this value in the variable V, which can be of type Integer, Real or Double. If the conversion isn't succesfull, then the parameter Code contains the index of the character in S which prevented the conversion.

4.8.1 System unit constants

```

        BLANK           = ' ';
maxint  = 2147483647;
pi      = 3.1415926535897932385;
MAXSTRING =255;
MAXREAL  =3.4E38;
MINREAL  =1.18E-38;
mindiv   =$80000;
EPSREAL  =1.0/mindiv;
MAXDOUBLE :double=1.79E308;
MINDOUBLE :double=2.23E-308;
        MAXCHAR  =chr(65535);
        MINCHAR  =chr(0);
NILSTR  ='';
        MAXLSTR  = 10000;
        MAXLOG   = 8.8029691931113054295988E1;    { log(2**127)  }
        MINLOG   = -8.872283911167299960540E1;    { log(2**-128) }
        LOG2E    = 1.4426950408889634073599;      { 1/log(2)    }
SEEK_SET =0;
SEEK_CUR =1;
SEEK_END =2;
minint64 =-9223372036854775807;
maxint64 =9223372036854775807;
PIO2     = 1.57079632679489661923;                { pi/2        }
PIO4     = 7.85398163397448309616E-1;            { pi/4        }
SQRT2    = 1.41421356237309504880;                { sqrt(2)     }

```

4.9 Libraries, static and dynamic

4.9.1 Linking to external libraries

It is possible to specify to which external libraries - that is to say libraries written in another language, a program should be linked by placing in the main program linkage directives. For example

```
{$linklib ncurses}
```

would cause the program to be linked to the ncurses library.

4.9.2 The export of procedures from libraries.

If a compilation unit is prefixed by the reserved word `library` rather than the words `program` or `unit`, then the procedure and function declarations in its interface part are made accessible to routines written in other languages.

4.9.3 Creating libraries

Depending on the linking that you do these Vector Pascal libraries can either be statically linked into a C program, or can form a Dynamic Link Library (DLL) which can be linked at runtime to the C code. What follows are two examples of how to do this.

Static Libraries

Static libraries can be used in either Linux or Windows systems. Building and using a library involves several stages and should be controlled by the use of make files.

Here is an example library:

```
library examplelib;
interface

  procedure exampleproc;

implementation

  procedure exampleproc;
  begin
    writeln(' procedure in library called');
  end;
end.
```

and here is an example C program that calls the library:

```
#include<stdio.h>
main(argc, argv)
{
  extern void examplelib_exampleproc();
  printf("start of C program \n");
  initfs();                      /* initialise the pascal runtime library
                                 for the dll version call initdll()*/
  examplelib_exampleproc();      /* call the library procedure */
  printf("end of C program\n");
}
```

In order to use the library from C we must do the following:

1. Compile the library to assembler language.
2. Use the gnu tools to assemble this to an object file.
3. Create an object file version of the pascal runtime library.
4. Link both of these with the C program that is going to use the library.

The steps could be performed by the following makefile:

```
CFLAGS=-g

all: uselib
    uselib

examplelib.s: examplelib.pas
    vpc examplelib -S -Aexamplelib.s -cpugnuPentium
#    compile the library to assembly language

examplelib.o: examplelib.s
    gcc $(CFLAGS) -c examplelib.s

rtl.o: rtl.c
    gcc $(CFLAGS) -DLIBRARY -c rtl.c
```

```
# compile it in a form suitable for use in a library

rtl.c: ../../mmpc/rtl.c
    cp ../../mmpc/rtl.c rtl.c
# get a copy of the pascal run time library
# from wherever we have installed the vector pascal system

uselib: uselib.c examplelib.o rtl.o
    gcc $(CFLAGS) uselib.c rtl.o examplelib.o -o uselib
# link the C program with the examplelib
```

DLLs

DLLs or Dynamic Link Libraries are a type of Windows file that can be linked to at runtime. Building them is more complex than a static library as one needs to write a .def file which defines which functions are to be exported from the DLL, and one must also build a stub library to which the main program can be linked. One can use the `gnu dlltool` to build the stub library.

We illustrate the process with a similar example. First the C program:

```
#include<stdio.h>
main(argc, argv)
{
printf("start\n");
dllinit();
exampledll_exampleproc();
}
```

Next the example DLL in Pascal:

```
library exampledll;
interface
  procedure exampleproc;
implementation
  procedure exampleproc;
  begin
    writeln(' procedure in dll called');
  end;
end.
```

We now provide a file `exampledll.def` file which tells the `gnu dlltool` which functions we want to export:

```
EXPORTS
exampledll_exampleproc
dllinit
```

Finally the make file:

```
CFLAGS=-mno-cygwin
# specify that cygwin gcc is to rely on the windows built in C libraries

all: usedll.exe exampledll.dll
    usedll
```

```

exampledll.s: exampledll.pas
    vpc exampledll -S -Aexampledll.s -U -cpugnuPentium

exampledll.o: exampledll.s
    gcc $(CFLAGS) -DBUILD_DLL -c exampledll.s

rtl.o: rtl.c
    gcc $(CFLAGS) -DBUILD_DLL -c rtl.c
# compile it in a form suitable for use in a dll

rtl.c: ../../mmpc/rtl.c
    cp ../../mmpc/rtl.c rtl.c
# get a copy of the pascal run time library

exports.o: exampledll.a

exampledll.a: exampledll.def makefile
    dlltool -v -e exports.o -l exampledll.a -d exampledll.def -D exampledll.dll exampledll.o rtl.o
# Note that you must use the -D option to tell dlltool the name of the dll you will build
# this also reads in the .def file it produces exampledll.a with which
# you statically link your c program ( it contains stubs to the real dynamic fns )

exampledll.dll: exports.o rtl.o exampledll.o
    gcc $(CFLAGS) -shared exports.o rtl.o exampledll.o -o exampledll.dll
# build the dll using the export spec produced by dlltool

usedll.o: usedll.c
    gcc $(CFLAGS) -c usedll.c
# compile the c program to an object file

usedll.exe: usedll.o exampledll.a
    gcc $(CFLAGS) usedll.o exampledll.a -o usedll
# link the c program with the exampledll stub library

```

4.9.4 Cross Language Parameter Passing

When calling Pascal from C observe the following rules:

- Atomic values of type integer and real can be passed as value parameters. Pascal type real corresponds to C type float.
- Composite values such as records arrays or strings should be passed as pascal var parameters, and in C call the address of the composite item must be passed.
- Strings in Vector Pascal are stored in 16 bit unicode preceded by a 16 bit length word. C strings are stored as arrays ASCII of bytes. If a Pascal procedure requires a string parameter, then the C code calling it must pack the string into an array of short.

Thus a Pascal procedure exported from library mylib and declared as follows

```

type intarray=array[0..99] of integer;
procedure foo(var s:string; r:real; var f:intarray);

```

would have the C prototype

```

extern void mylib_foo(short *, float, int *);

```


Chapter 5

Implementation issues

The compiler is implemented in java to ease portability between operating systems.

5.1 Using Unicode with Vector Pascal

ISO Pascal is defined using an alphabet of symbols all of which can be represented with ASCII. Vector Pascal uses Unicode to permit a wider range of symbols to be used in programs.

Programs should be submitted to the compiler in UTF-8 encoded Unicode. Since the 7 bit ASCII is a subset of UTF-8, all valid ASCII encoded Vector Pascal programs are also valid UTF-8 programs.

5.1.1 Letter based Identifiers

ISO Pascal allows the Latin letters A-Z to be used in identifiers. Vector Pascal extends this by allowing letters from the Greek, Cyrillic, Katakana and Hiragana character sets.

Alphabet	Position	glyph	code
Greek	low	Α	0391
	high	Ω	03a9
Cyrillic	low	А	0410
	high	Я	042f
Katakana	low	ア	30a0
	high	ヱ	30fa
Hiragana	low	ぁ	3041
	high	づ	0394

Treatment of identifiers is case indifferent, in that upper case and lower case versions of a given letter are treated as equivalent. Thus the identifier δ may also be written Δ. Identifiers drawn from these alphabets can be strings of letters or digits starting with a letter.

5.1.2 Ideographic identifiers

Vector Pascal allows the use of Ideographs drawn from the unified Chinese, Japanese and Korean sets (Unicode range 4e00-9fff) to act as identifiers.

5.1.3 Special Symbols

When using Unicode certain mathematical operations that are encoded as a sequence of ASCII characters can be represented as a single Unicode character.

Operation	ASCII form	Extended form	Unicode
Set membership	in	∈	2208
Assignment	:=	←	2190
Integer division	div	÷	00f7
Nary summation	\+	∑	2211
Nary product	*	∏	220f
Square root	sqrt	√	221a
Less than or equal	<=	≤	2264
Greater than or equal	>=	≥	2265
Not equal	< >	≠	2260
Negation	not	¬	00ac
Logical and	and	∧	2227
Logical or	or	∨	2228
Multiplication	*	×	2715
Index generation	iota	ι	2373

Example The following shows the use of Unicode operators in place of the Ascii ones used on early releases of Vector Pascal.

```

Program proddemo;
{ prints the product and square root of the integers 1..5 }
Var a:array[1..5] of Integer; Y:integer;
Begin
  { unicode version }
  a ← ι 0; { form integers from 1 to 5 }
  Writeln(a);
  Y ← ∏ a; { get their product }
  Writeln( y, √y);
  { now using ascii }
  a:= iota 0;
  writeln(a);
  y:= \* a;
  writeln( y, sqrt(y));
End.

```

Characters The built in char type in Pascal is represented with 16 bits in Vector Pascal. This allows any Unicode character to be handled.

Strings Strings are held as arrays of char with a length word held in the first character. This is a simple extension of the mechanism used in Turbo Pascal. It potentially allows strings to be up to 65535 characters long. The type STRING written without a length specification stands for a string of length MAXSTRING.

Read When reading strings or characters from a text file, conversion is automatically performed from utf-8 to Unicode format.

Write When characters or strings are output to a text file, they are converted from the internal Unicode format to the utf-8 format.

5.2 Invoking the compiler

The compiler is invoked with the command

```
vpc filename
```

where filename is the name of a Pascal program or unit. For example

```
vpc test
```

will compile the program test.pas and generate an executable file test, (test.exe under windows). The full usage is:

```
vpc srcname [options] [non pascal files]
```

- srcname should not include the .pas extension
- output will be in an executable srcname.exe for Windows or simply srcname for Linux

Non Pascal files you can supply a list of .a, .o, .s or .c files that are to be compiled and linked with your program this is typically done to give a Pascal program access to libraries written in another language

The command vpc is a shell script which invokes the java runtime system to execute a .jar file containing the compiler classes. Instead of running vpc the java interpreter can be directly invoked as follows

```
java -jar mmpc.jar filename
```

The vpc script sets various compiler options appropriate to the operating system being used.

5.2.1 Environment variable

The environment variable mmpcdir must be set to the directory which contains the mmpc.jar file, the runtime library rtl.o and the system.pas file.

5.2.2 Compiler options

The following flags can be supplied to the compiler :

```
-A<asmfile>    Allows you to specify the assembler file name used

-BOEHM
link with the BOEHM garbage collector which must
be installed in your gcc linkage path
-NOBOEHM       default
-coresN        generate code for N cores executing in parallel
-cpu<NAME>     specifies the code generator to be used in compiling
code. Default on 64 bit systems is AMD64, other available <NAME>s include
  AMD64 - AMD64 bit instructions using SSE2 and gas
  AVX64 - AVX instructions 64 bit address space using NASM
  AVX32 - AVX instructions 32 bit address space using NASM
  C      - translates Pascal to 32 bit C and compiles with gcc
```

```

EE      - for Sony PS2 Emotion Engine ( cross compiler )
gnuPentium, gnu486 intel 32 bit processors but using gas
IA32   - Intel 486 using NASM - no SIMD use
P3     - Intel 32 bit with SSE1 using NASM
P4     - Intel 32 bit with SSE2 using NASM
Opteron - version of Opteron code generator without PIC needs gcc-4.8
MIC    - Intel XeonPhi with 64 bit code
-fastforloop Does more optimisation of for loops, this form of loop will not
            terminate correctly if the limit to the loop = MAXINT
-NOVPWORDS Allows Vector Pascal reserved words that do not occur in Turbo
            or in Extended Pascal to be used as identifiers
-D<symbol> Define compiler pre-processor flag for conditional compilation
-d<symbol> Define the directory path in which to find files
-fcoff Get assembler to generate coff output
-felf Get assembler to generate elf output
-gnu generate assembler using the gnu Pentium assembler

?
-h
-help
--h
--help print this text
-inter generate an intermediate ilc file for the syntax tree
-parallelsum attempt to evaluate \+ in parallel
        -L
-L<digit>Output a Latex listing of the program with variable levels
of detail included
-nobalance switches off canonical re-ordering of expression trees
-nolink      switdches off linking so that a .o file is generated
-o<filename> Specifies the name of the object file generated by
the assembler pass
-opt<decimal number> select an optimisation level in range 0..31, default is 1.
        The number is a sum of powers of 2 which switch on
        distinct optimisations.
    1 Subexpression optimiser, common sub expressions in a statement
      are evaluated once.
    2 removeloopinvariants, invariant statements or expressions in implicit
      or explicit loops are taken out of loop and executed first.
      This will involve allocating implicit loop variables which can be
      register optimised by CacheLocals
    4 unrollLoops, short loops replaced with inline code, longer ones have
      multiple logical iterations for each actual jump to the start of the
      unrolled loop.
    8 CacheLocals, implicit local variables that have been
      allocated for array expressions are allocated to registers.
    16 Try alternatives, generate several possible instruction sequences using
      different opcodes with the same semantics and chose the shortest.
-S Generate an assembler output but do not assemble or link
-T Run in training mode, do not load any of the pre-learned
code generation tactics stored in the .vwu file
-U Generate underlines as prefix for external symbols to the
        linker
Compiler development options
-V switch on verbose mode for entire compilation

```

```

-switchon<number>
switch on verbose mode whilst generate src line <number>
-switchon<nuber>..<number>
switch on verbose mode between range of lines
        in source when code generating code
-cputest do not compile a program but send test patterns
to the code generator to test what arithmetic
operations it can do and print the result to
the standard output

```

5.2.3 Dependencies

The Glasgow Pascal Compiler depends upon a number of other utilities which are usually pre-installed on Linux systems, and are freely available for Windows systems.

NASM	The net-wide assembler. This is used to convert the output of the code generator to linkable modules. It is freely available on the web for Windows. For the Pentium processor it is possible to use the <code>as</code> assembler instead.
gcc	The GNU C Compiler, used to compile the run time library and to link modules produced by the assembler to the run time library.
java	The java virtual machine must be available to interpret the compiler. There are number of java interpreters and just in time compilers are freely available for Windows.
nvcc	The nvidia CUDA compiler, required if compiling for an Nvidia GPU. Part of the free Nvidia toolkit download.

5.3 Procedure and function mechanism

5.3.1 Requirements

1. Must be able to call C routines as well as Pascal ones.
2. Must establish a name correspondence with C routines that we call externally.
3. Must pass parameters appropriately
4. Must get results back from C routines

Name correspondance

name correspondance with the C routine

Issues here

1. Case of the names
2. allowed characters
3. how are these passed in assembler

Characters and significance

Case is significant both in C, but this is not the case of all languages.

Pascal for instance makes case insignificant, and requires that externals where the case is significant be given a name in quotes for example:

```
procedure close (var f:fileptr);
external name 'pasclose';
```

This allows the external routine to have a different name to the internal representation of it. The allowed characters in a name in Hi are limited to the letters, that means we can not call and C routine with an `_` or a digit in its name unless we were to extend the syntax for externals along the above lines.

Assembler representation

In the assembler file, the compiler must list all the externals as follows (note this is the Nasm syntax, it will be different for other assemblers):

```
extern vconcat
extern iota
extern putchar
extern getnum
extern getchar
extern putnum
```

Then we can call them just as if they were declared within this file.

```
call vconcat
```

Underscores

Most 32-bit C compilers share the convention used by 16-bit compilers, that the names of all global symbols (functions or data) they define are formed by prefixing an underscore to the name as it appears in the C program.

However, not all of them do: the 'ELF' specification states that C symbols do **not** have a leading underscore on their assembly-language names.

Thus if you are producing code for Linux, which uses ELF, do not use underscores.

In Vector Pascal the `-U` flag on the command line selects whether leading underscores are to be generated.

5.3.2 The C calling convention

Before explaining the Vector Pascal function calling technique we present, the simpler technique used in C and that could be used in Pascal if there were no nesting of procedures. The convention used in diagrams in this section is that low addresses are show at the top of the page and high addresses at the bottom.

To call a C function, whether from C or from Pascal the following must be done.

1. The caller pushes the function's parameters on the stack, one after another, in reverse order (right to left, so that the first argument specified to the function is pushed last).
2. The caller then executes a near 'CALL' instruction to pass control to the callee.

3. The callee receives control, and typically (although this is not actually necessary, in functions which do not need to access their parameters) starts by saving the value of 'ESP' in 'EBP' so as to be able to use 'EBP' as a base pointer to find its parameters on the stack. However, the caller was probably doing this too, so part of the calling convention states that 'EBP' must be preserved by any C function. Hence the callee, if it is going to set up 'EBP' as a frame pointer, must push the previous value first.
4. The callee may then access its parameters relative to 'EBP'. The doubleword at '[EBP]' holds the previous value of 'EBP' as it was pushed; the next doubleword, at '[EBP+4]', holds the return address, pushed implicitly by 'CALL'. The parameters start after that, at '[EBP+8]'. The leftmost parameter of the function, since it was pushed last, is accessible at this offset from 'EBP'; the others follow, at successively greater offsets. Thus, in a function such as 'printf' which takes a variable number of parameters, the pushing of the parameters in reverse order means that the function knows where to find its first parameter, which tells it the number and type of the remaining ones.
5. The callee may also wish to decrease 'ESP' further, so as to allocate space on the stack for local variables, which will then be accessible at negative offsets from 'EBP'.
6. The callee, if it wishes to return a value to the caller, should leave the value in 'AL', 'AX' or 'EAX' depending on the size of the value. Floating-point results are typically returned in 'ST0'.
7. Once the callee has finished processing, it restores 'ESP' from 'EBP' if it had allocated local stack space, then pops the previous value of 'EBP', and returns via 'RET'.
8. When the caller regains control from the callee, the function parameters are still on the stack, so it typically adds an immediate constant to 'ESP' to remove them (instead of executing a number of slow 'POP' instructions). Thus, if a function is accidentally called with the wrong number of parameters due to a prototype mismatch, the stack will still be returned to a sensible state since the caller, which `_knows_` how many parameters it pushed, does the removing.

consider the Pascal code:

```

var zot:record  x,y:integer; z:double; end;
function foo( x,y:integer; z:double):integer;begin foo:=x+y end;
procedure bar;
var  x, y:integer;
      z:double ;
begin
  x:=foo(1,2,3.0);
end

```

The memory allocation, if nested functions did not exist in Pascal, could be implemented as shown in figure 5.1.

Note that the addresses of parameters and variables can be specified relative either to a special register called the frame pointer or to the stack pointer. If your code does not dynamically push things onto the stack or if your compiler keeps track of the stack position, then the SP register may be preferred. In Vector Pascal however, as is conventional with most other Pascal compilers we use the Frame Pointer register to access parameters and variables.

Key points:

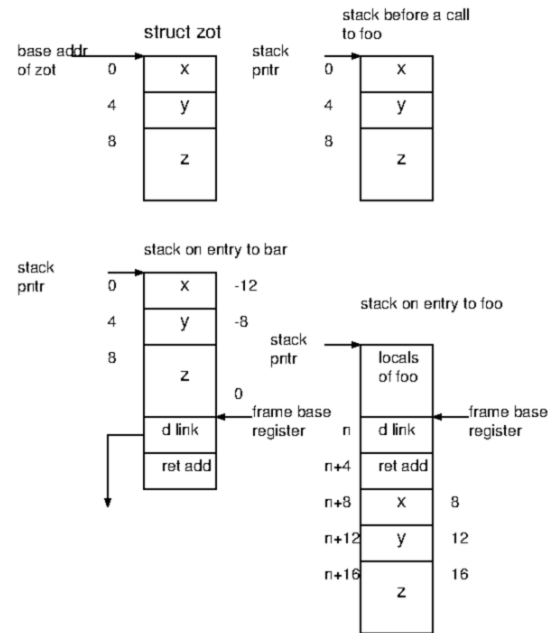


Figure 5.1: Stacks and records

1. If you address via the frame pointer (EBP on a Pentium) then the parameters have +ve addresses and the locals have -ve addresses.
2. If you address using the stack pointer they all have +ve addresses.
3. If you use the SP (ESP on a Pentium) the compiler has to take into account temporaries that are pushed on the stack.

5.3.3 Var Params

We have been assuming value parameters.

If we have var parameters (parameters which, when assigned to, change the value of the actual parameter) then the address of the parameter rather than the value of the parameter has to be passed on the stack. The compiler then places an extra level of indirection onto the addressing of the parameter.

5.3.4 Nested Functions

The existence of nesting of functions and procedures generates complexities that force us to use a more elaborate calling method than C. Consider the following Pascal example where we allow function nesting.

```

type vec1 = array[1..10] of integer;
      scalar = integer;
function sum(var v:vec1);scalar;
  function total( i:scalar):scalar;
  begin
    total:=if i<1 then 0 else v[i]+total(i-1);
  end
  total(length(v))

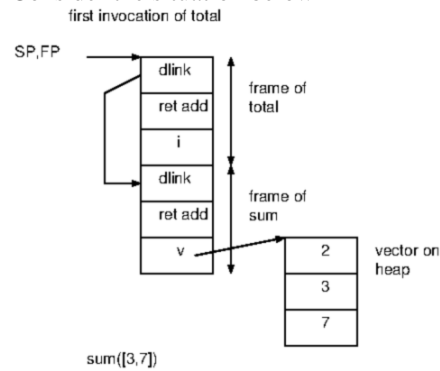
```

Total recurses on i , but each invocation accesses the same copy of v .

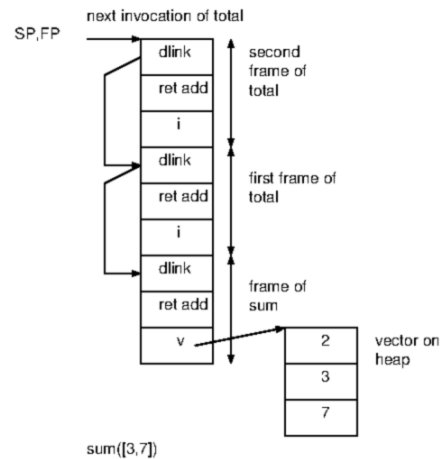
Can we use the d-link to access v ?

No

Consider the situation below



At this point we can access v at $\text{mem}[\text{dlink}+8]$, but what happens on the next recursion?



if we use $\text{mem}[\text{dlink}+8]$ we get the previous version of i , v is now at $\text{mem}[\text{mem}[\text{dlink}]+8]$

We need an alternative approach. There are 3 practical alternatives:

- Displays
- Static Links
- Lambda Lifting

We have chosen to use displays since Intel hardware provides support for these. They do place slight restrictions on function parameters¹, but it was felt that the simplicity of display implementation, and the ability to use the same calling mechanism as C outweighed this.

Displays

These can use the Intel Enter instruction defined as:

```

enter storage, level
push ebp
temp:=esp
if level>0
then

```

¹A functions f may not be an actual parameter to procedure or function g , if the scope of g outer to that of f

```

repeat (level-1) times
  ebp:=ebp-4
  push dword[ebp]
end repeat
push temp
fi
ebp:=temp
esp:=esp - storage

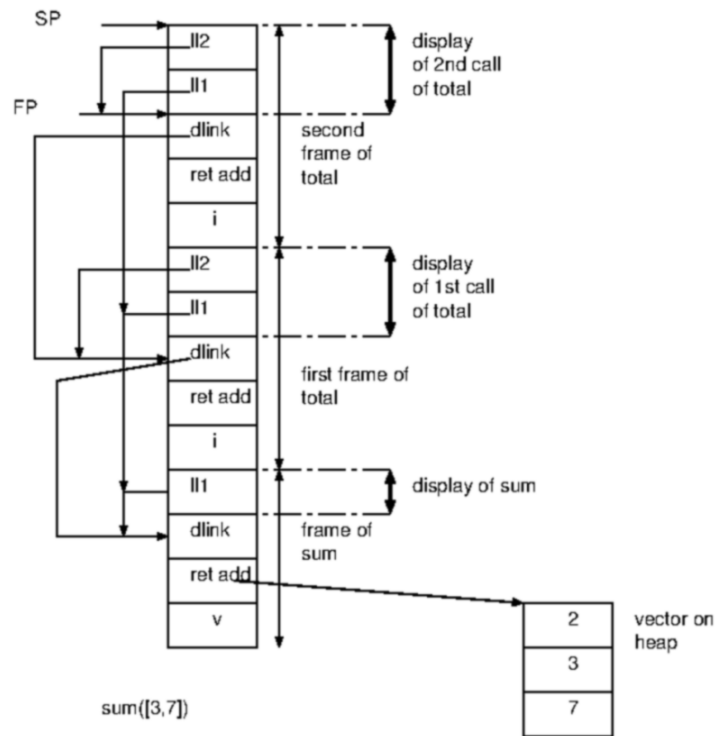
```

For machines other than the Intel family, you, as a compiler modifier, have to generate sequences of simpler instructions to emulate the Intel Enter instruction.

Up to now we have assumed procedures use

```
enter xxx,0
```

Consider the effect of using enter 0,1 for sum and enter 0,2 for total :



All variables are now addressed as a pair (lexlevel,offset), where an outer level function is lexical level 1, the first nested function is lexical level 2 etc.

A parameter can now be addressed as

```
mem[ display[lexlevel]+offset]
```

The display is an array in memory at the start of the current frame. Using this notation, parameter `i` is always addressed as

```
mem[display[2]+8]= mem[ mem[fp-8]+8]
```

and `v` is always at

```
mem[display[1]+8]
```

hh

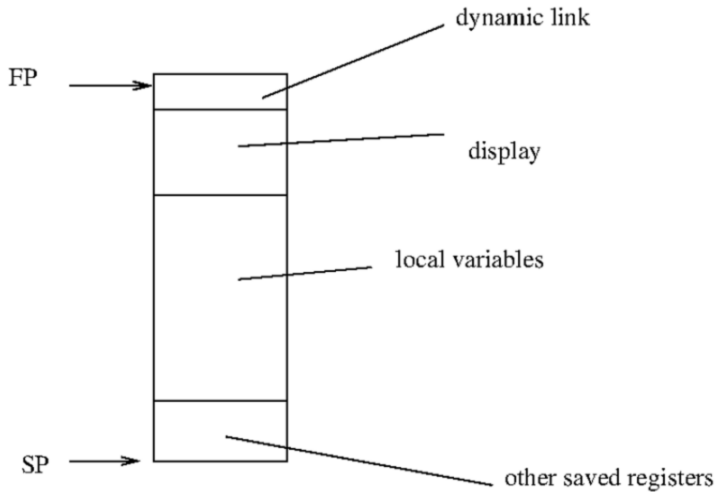


Figure 5.2: Full stack frame layout

Optimisations FP always points to the current lexical level so at lexical level 2 we have

```
mem[display[2]+8]
= mem[ mem[fp-8]+8]
= mem[fp+8]
```

Likewise we can choose to cache other display values in registers so avoiding repeated dereferencing of the display on stack.

Other registers sometimes have to be saved because of the definition of the ABI of the processor. If this is the case then they are saved after space has been reserved for local variables as shown in Figure 5.2.

5.3.5 Detail of calling method used on the Pentium

Procedure parameters are passed using a modified C calling convention to facilitate calls to external C procedures. Parameters are pushed on to the stack from right to left. Value parameters are pushed entire onto the stack, var parameters are pushed as addresses.

Example

```
program callconv;
type t1= record a,b:integer end;
var
  x,y:t1;
  procedure foo(var a:t1; b:t1; c:integer);
  begin
  end;

  function bar:t1;
  begin bar:=y;end;

begin
  x:=bar;
  foo(x,y,3);
end.
```

This would generate the following code for the procedure foo.

```

; procedure generated by code generator class ilcg.tree.PentiumCG;0
label114b8f429f3a;0
;   foo;0
; entering a procedure at lexical level 1;0
enter spaceforfool1-4*1,1;   create display and variable space
    push ebx;                save registers as demanded by Linux ABI
    push esi;
    push edi;
; -----                    Code for Foo would go here if
;-----                    it were not a null procedure

spaceforfool1 equ 4;        declare space needed this is done here
;                            because the code generation may cause
;                            new temporary vars to be needed so
;                            we dont know the space required to here

foollexit;2
    pop edi;                 restore saved registers
    pop esi;0
    pop ebx;0
leave;                       restore old stack frame
ret 0;                       pop return address into PC

```

and the calling code is

```

push DWORD    3;            right most parameter 3
lea esp,[ esp+   -8];      create space for y on stack
movq MM4, [ PmainBase+  -16];  fetch y
movq [ esp],MM4;          store on the stack
push DWORD PmainBase+   -8;   push the address of x
EMMS ;                   clear mmx status flags
call label114b8f429f3a;    call the procedure
add esp, 16;              restore the stack

```

Function results

Function results are returned in registers for scalars following the C calling convention for the operating system on which the compiler is implemented. Records, strings and sets are returned by the caller passing an implicit parameter containing the address of a temporary buffer in the calling environment into which the result can be assigned. Given the following program

The call of bar in the previous example would generate

```

push DWORD PmainBase+   -24;   pass the address of a result buffer
call label114b8f429f712;      call the function
add esp, 4;                   restore the stack
movq MM4, [ PmainBase+   -24];  get the result buffer in MM4
movq [ PmainBase+   -8],MM4;   store in x

```

5.4 Multi-core Parallelism

SIMD vectorisation works for one dimensional data, or on the last dimension for arrays stored in row major order, because the hardware has to work on adjacent words. SIMD

Algorithm 5.1 Example of combined multi-core and SIMD parallelism.

```

procedure sub2d;
type range=0..127;
var x,y,z:array[range,range] of real;
begin
    x:=y-z;
end;

```

This translates into ILCG as follows when compiled for a dual core Opteron

```

procedure (sub2d,
procedure (label12 ... see Algorithm 5.2 )
post_job[label12,^(%rbp),1]; /* send to core 1 */
/* Note that %rbp is the Opteron stack frame pointer */
post_job[label12,^(%rbp),0]; /* send to core 0 */
wait_on_done[0];
wait_on_done[1];
)

```

gives considerable acceleration on image data, and worthwhile accelerations on floating point and integer data. Future machines like the Larrabee will have considerably wider SIMD registers, increasing the benefits of SIMD code. But newer chips also have multiple cores. For these, the recent versions of the Glasgow Pascal Compiler will parallelise across multiple cores if the arrays being worked on are of rank 2. The Pascal source code of the program remains the same independently of whether it is being targeted at a simple sequential machine, a SIMD machine or a multi-core SIMD machine. Targeting is done by flags passed to the compiler:

```
vpc sub2dex -cpu486
```

would compile sub2dex.pas using purely sequential 32 bit instructions.

```
vpc sub2dex -cpuOpteron
```

would compile the same file targeted to a 64 bit Opteron with 1 core using the SIMD instructions in the Opteron instructionset.

```
vpc sub2dex -cpuOpteron -cores2
```

would compile the file to a 64 bit Opteron with 2 cores and SIMD instructions. The compiler is implemented in Java so the selection of code generators and compilation strategies is achieved by dynamically loading appropriate compiler and code generator classes.

Let us now look at the transformations required to achieve this using a trivial rank 2 array example in Algorithm 5.1. The example is not intended to be realistic or useful, only illustrative. We assume that the code has been compiled for a dual core Opteron.

Two threads are dispatched to process the work using a fork - rejoin paradigm. The run time library is built on top of pthreads. For a two core machine, two server threads are initiated at program start up. These wait on a semaphore until post_job passes them the address of a procedure and a stack frame context within which the procedure is to be executed.

The statement $x:=y-z$ is translated into a procedure that can run as a separate task, the ILCG has been simplified for comprehensibility in Algorithm 5.2.

The basic structure of the task procedure is two nested for loops, one for each dimension of the arrays.

Algorithm 5.2 The function performing nested loops.

```

procedure (label12 /* internal label*/ ,
for (mem(+(^(%rbp),-24)),^(mem(+(^(%rbp),16))),127 , 2,
/*iota [0]          task number      limit  step*/
var (mem(+(^(%rbp),-32)),/* iota[1] */
for (mem(+(^(%rbp),-32)), 0 ,127, 4 ,
/*iota [1]          start limit  step*/
mem(ref ieee32 vector ( 4 ), /* x[iota[0],iota[1]] */
+(* (^ (mem(+(^(%rbp),-24))),512),
+(* (^ (mem(+(^(%rbp),-32))), 4),-131072)),
^ (mem(+(^(%rbp),-8))))):=
-(^ (mem(ref ieee32 vector ( 4 ),/* y[iota[0],iota[1]] */
+(* (^ (mem(+(^(%rbp),-24))),512),
+(* (^ (mem(+(^(%rbp),-32))), 4),-196608)),
^ (mem(+(^(%rbp),-8))))),
^ (mem(ref ieee32 vector ( 4 ),/* z[iota[0],iota[1]] */
+(* (^ (mem(+(^(%rbp), -24))),512),
+(* (^ (mem(+(^(%rbp), -32))), 4),-262144)),
^ (mem(+(^(%rbp),-8))))))))))
)

```

The outer loop or row index steps by 2 to ensure that each task will process every 2nd row, starting at the row given by the task number. Thus task 0 will process rows 0,2,4,6,... Task 1 will process rows 1,3,5,7,... If there are 4 cores available each task will process every 4th row, etc.

The inner loop, for the column indices, advances by 4 since the Opteron has SIMD registers capable of handling 4 floating point numbers at a time.

5.4.1 The PURE Function Extension

We define a pure function to be such that does not have any side effects, i.e. it does not update any global, or shared, states outside of its own scope. If the other functions are called from the body of the function, these also have to be pure even if not marked as such. This definition of pure functions is consistent with the definition used in FORTRAN 95. Given the absence of explicit multi-threading constructs in the given language, the above property of pure functions implies thread safety. A function can be labeled as pure by prepending the keyword `pure` in front of every declaration or definition of the function. This means that if, for example, a function is declared as pure in the interface section of the programme, it must be also declared as pure anywhere else in the code, e.g. in the subsequent definition of the function body. Any inconsistency in the declared purity of a function is spotted by the compiler and treated as a syntactic error.

```

pure function next(i : integer): integer;
begin
    next := i+1;
end;

```

Above function `next` operates only on the parameter passed to it, thus it is appropriate to declare it as pure. The keyword `pure` does not bare any semantic value, other than it serves as a hint to the compiler which may then generate multi-threaded code. Multi-threaded code will be generated if `-coresn` flag is passed to the compiler specifying more than one core, and hence the number of threads, available to the programme and if the function is then invoked as part of an assignment statement.

5.4.2 Task Parallelism and Block Structure

The technique of procedurising code shown in Algorithms 5.1 and 5.2 is well established when parallelising loops in Open-MP. There are two significant differences. First, and

Algorithm 5.3 Taylor series example.

```

program nestpar;
type t = array[1..3,1..2] of real;
  coef=array[0..5] of real;
      { tabulate inverse factorials }
const expc:coef=(1,1,1/2,1/6,1/24,1/(5*24));
var scale:real;B:t;
procedure emap(var a:t);
  { for each a[i,j] replace with a[i,j]+exp(scale*a[i,j]) }
  var coefs:coef;
  pure function Taylor( x:real):real;
  begin
    Taylor:= \+ (coefs * x pow iota[0]);
  end;
begin
  coefs:= expc;
  a := Taylor(a*scale);
end;
begin
  scale:=0.1;
  B:= iota[0]*iota[1];
  write(B);
  emap(B);
  write(B);
end.

```

Output Produced

1.00000	2.00000
2.00000	4.00000
3.00000	6.00000
1.10517	1.22140
1.22140	1.49182
1.34986	1.82205

least significantly, in Vector Pascal the loop is implicit rather than the explicit loops used in Open-MP. But secondly Open-MP is targeted at C and FORTRAN which are flat languages. Pascal is a block structured language which makes the access to variables by spawned tasks somewhat more complex. Consider Algorithm 5.4.2 which illustrates the use of nested blocks in Pascal. This has a main program `nestpar` and embedded within that a procedure `emap` which takes a matrix a as a parameter and replaces each $a_{i,j}$ with $e^{scale \cdot a_{i,j}}$ where $scale$ is a global variable. The exponential function is approximated by a Taylor series

$$e^x = 1 + \frac{1}{1!}x^1 + \frac{1}{1!}x^1 + \frac{1}{2!}x^2 + \frac{1}{3!}x^3 + \dots$$

using the function `Taylor`. The Taylor series is evaluated as

$Taylor \leftarrow \sum (coefs \times x^{t_0})$;

where $t_0 = 0, 1, 2, 3, \dots$ using the line

```
Taylor:= \+ (coefs * x pow iota[0]);
```

The `coefs` vector has been initialised in the main program to contain the inverse factorial series as required.

There are a number of references from inner to outer scopes: `Taylor` uses the vector `coefs`, and `emap` uses the variable `scale`. There are three well known techniques for implementing this in normal procedural code: λ lifting, static chaining or display vectors. Since Intel provide direct hardware support for display vectors in the procedure `ENTER` and `LEAVE` instructions we have chosen to use displays. Figure 5.3 illustrates how the stack would be organised during execution of `Taylor` when the program is compiled for

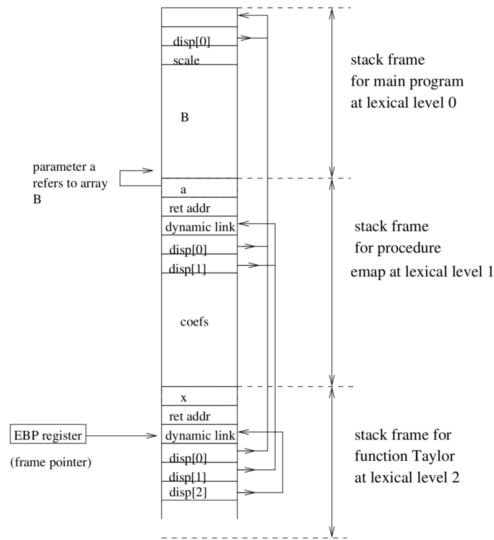


Figure 5.3: Stack for nester in single core mode.

a single core machine. Observe how Taylor can access variables in the enclosing stack frames using the display vector. But if the code is to run on a dual core machine there will be not one but three stacks as shown in Figure 5.4: one for the main program and one each for the child tasks. The original function `emap` will have been written to ILCG equivalent to:

```

procedure emap(var a:t;
  var coefs:coef;
  pure function Taylor( x:real):real;
begin
  Taylor:= \+ (coefs * x pow iota[0]);
end;
procedure dummy(start:int);
var iota:array[0..1] of integer;
begin
  iota[0]:=start;
  while iota[0]<=3 do
  begin
    for iota[1]:=1 to 2 do
      a[iota[0],iota[1]]:=Taylor(a[iota[0],iota[1]]*scale);
      iota[0]:=iota[0]+2;
    end;
  end;
begin
  coefs:= expc;
  post_job(dummy,1);post_job(dummy,0);
  wait_on_done(0);wait_on_done(1);
end;

```

The function `dummy` has to run on a task stack and yet have access to the variable `a` in `emap` and `scale` in the main program, both of which are executing on the main stack. It then has to call `Taylor` in such a way as to ensure that `Taylor` can access the global `scale`. Provided that the displays can be set up as shown in Figure 5.4, this will work, but it is impossible to set up the displays this way when using standard intel call conventions along with the `pthread`s library. Whenever a function is executed within a thread it is allocated a new stack that does not contain display pointers, hence variables from containing scopes cannot be accessed.

In order to support sharing of the global stack amongst multiple tasks, we have implemented an assembly routine `taskexecute`, which corresponds to the following C function

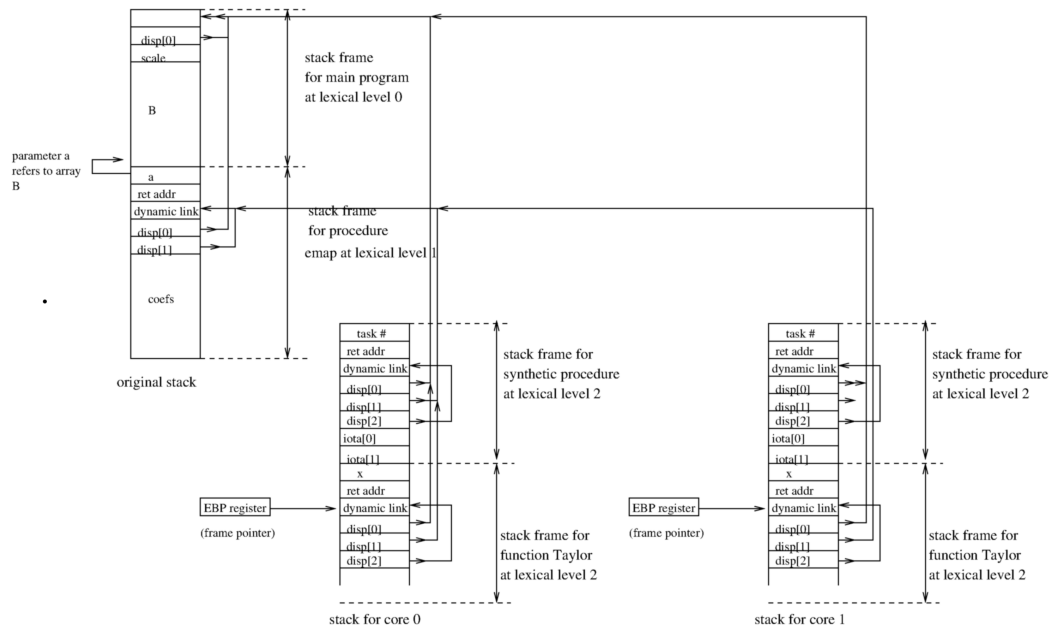


Figure 5.4: The 3 stacks used by nestpar in dual core mode.

signature:

```
void taskexecute(struct threadblock *);
```

As can be seen, the function expects a single parameter which is a pointer to a structure of type *struct threadblock* defined as

```
struct threadblock{
    char * savedframepointer;
    char * savedcodepointer;
    int threadnumber;
}
```

Above, *savedframepointer* is the pointer to the original stack in which the displays are already setup, *savedcodepointer* is the pointer to the function that is being parallelised, and *threadnumber* is a number in the range $0..n - 1$ for a programme running on n cores.. The following assembly code implements *taskexecute* on the Pentium architecture.

Assembly code sequence required to implement the task execute

```
.globl taskexecute
taskexecute:
# on entry we have a pointer in %esp to the task block
# this task block has the C definition
# struct threadblock{
#     char * savedframepointer;
#     char * savedcodepointer;
#     int threadnumber;}
# the first thing we do is save the framepointer on entry
push %ebp
# next get the address of the stored frame pointer in the task block
mov 8(%esp) , %eax
#we load the frame pointer into the hardware frame pointer (ebp)
mov 0(%eax), %ebp
```

```

# get the task number
push 8(%eax)
# make the call on the task
call * 4(%eax)
# unwind stack pointer
add $4,%esp
# restore framepointer we were called with
pop %ebp
ret

```

The essence of this form of implementation is that the pthread is setup to execute `taskexecute` which is passed `threadblock` from the calling environment that contains the stack pointer used by the calling environment. `taskexecute` substitutes the stack allocated by the pthread library with the above stack before executing the code sequence contained in the `savedcodepointer`. The effect of substituting the stack pointer is undone once the called code sequence halts to ensure a clean exit of the wrapper.

5.5 Example Programs

5.5.1 Image convolution

The first example we will look at is the use of a separable convolution kernel to blur an image. Convolution of an image by a matrix of real numbers can be used to smooth or sharpen an image, depending on the matrix used. If A is an output image, K a convolution matrix, then if B is the convolved image

$$B_{y,x} = \sum_i \sum_j A_{y+i,x+j} K_{i,j}$$

A separable convolution kernel is a vector of real numbers that can be applied independently to the rows and columns of an image to provide filtering. It is a specialisation of the more general convolution matrix, but is algorithmically more efficient to implement. We can do a separable convolution provided that the kernel is formed by the outer product of two vectors \mathbf{a}, \mathbf{b} . A symmetric separable convolution can be done if $\mathbf{a} = \mathbf{b}$.

If \mathbf{k} is a symmetric separable convolution vector, then the corresponding matrix K is such that $K_{i,j} = \mathbf{k}_i \mathbf{k}_j$.

Given a starting image A as a two dimensional array of pixels, and a three element kernel c_1, c_2, c_3 , the algorithm first forms a temporary array T whose whose elements are the weighted sum of adjacent rows $T_{y,x} = c_1 A_{y-1,x} + c_2 A_{y,x} + c_3 A_{y+1,x}$. Then in a second phase it sets the original image to be the weighted sum of the columns of the temporary array: $A_{y,x} = c_1 T_{y,x-1} + c_2 T_{y,x} + c_3 T_{y,x+1}$.

Clearly the outer edges of the image are a special case, since the convolution is defined over the neighbours of the pixel, and the pixels along the boundaries a missing one neighbour. A number of solutions are available for this, but for simplicity we will perform only vertical convolutions on the left and right edges and horizontal convolutions on the top and bottom lines of the image. A Vector Pascal routine to do this is given below. The source has been pretty printed in the latex format that is automatically generated by the compiler is listing enabled. An equivalent sequential C routine is given in Algorithm 5.4.

In comparing the C and Vector Pascal, note two features which give performance advantages to the Vector Pascal form of the algorithm.

1. The support for fixed point 8 bit arithmetic with the pixel type. This allows a higher level of parallelism to be achieved since a P4 or AMD64 can in principle operate on 16×8 bit numbers with a single instruction. Lacking these types, the C algorithm has to use 32 bit floats. The pixel type automatically uses saturated arithmetic.
2. The data parallel form of expression of the Vector Pascal allows more efficient optimisation of the code.

Vector Pascal convolution algorithm**type**

```
plane(rows,cols:integer)= array [0..rows,0..cols] of pixel ;
```

var

```
Let  $T, l \in \hat{\text{plane}}$ ;
```

```
Let  $i \in \text{integer}$ ;
```

begin

Allocates a temporary buffer to hold a plane, and 3 temporary buffers to hold the convolution co-ordinates as lines of pixels.

```
new ( T ,im .maxrow ,im .maxcol );
```

```
new ( l ,3,im .maxcol );
```

```
l↑[0]← c1;
```

```
l↑[1]← c2;
```

```
l↑[2]← c3;
```

Perform convolution on each of the planes of the image. This has to be done with an explicit loop as array maps only works with functions not with procedures.

```
for  $i \leftarrow 0$  to  $im.maxplane$  do  $convpar (im_i, l \uparrow, T \uparrow)$ ; { see section 5.5.1}
```

This sequence frees the temporary buffers used in the convolution process.

```
dispose ( l );
```

```
dispose ( T );
```

```
end ;
```

convpar

```
procedure  $convpar ( \text{var } p, l, T : \text{plane} )$ ;
```

This convolves a plane by applying the vertical and horizontal convolutions in turn.

var

```
Let  $r, c \in \text{integer}$ ;
```

begin

This sequence performs a vertical convolution of the rows of the plane p and places the result in the temporary plane T . It uses the lines of pixels $l[i]$ as convolution weights. Use of lines of pixels rather than the floating point numbers for the kernel weights allows the computation to proceed 8 pixels at a time in parallel. The lines $T_0 \leftarrow p_0$; and $T_r \leftarrow p_r$; deal with the top and bottom rows of the picture which are left unchanged.

```

{$r-}{disable range checks}
r ← p.rows;
T1..r-1 ← p0..r-2 × l0 + p1..r-1 × l1 + p2..r × l2;
T0 ← p0;
Tr ← pr;

```

Now perform a horizontal convolution of the plane T and place the result in p .

```

c ← p.cols;
p0..r,1..c-1 ← T0..r,0..c-2 × l0 + T0..r,2..c × l2 + T0..r,1..c-1 × l1;
p0..r,0 ← T0..r,0;
p0..r,c ← T0..r,c;
{$r+}{enable range checks}

```

end ;

5.6 Array representation

The maximum number of array dimensions supported in the compiler is 5.

A static array is represented simply by the number of bytes required to store the array being allocated in the global segment or on the stack.

A dynamic array is always represented on the heap. Since its rank is known to the compiler what needs to be stored at run time are the bounds and the means to access it. For simplicity we make the format of dynamic and conformant arrays the same. Thus for schema

```
s(a,b,c,d:integer)= array[a..b,c..d] of integer
```

whose run time bounds are evaluated to be 2..4,3..7 we would have the following structure:

address	field	value
x	base of data	address of first integer in the array
x+4	a	2
x+8	b	4
x+12	step	20
x+16	c	3
x+20	d	7

The base address for a schematic array on the heap, will point at the first byte after the array header shown. For a conformant array, it will point at the first data byte of the array or array range being passed as a parameter. The step field specifies the length of an element of the second dimension in bytes. It is included to allow for the case where we have a conformant array formal parameter

```
x:array[a..b:integer,c..d:integer] of integer
```

to which we pass as actual parameter the range

```
p[2..4,3..7]
```

as actual parameter, where p :array[1..10,1..10] of integer

In this case the base address would point at @p[2,3] and the step would be 40 - the length of 10 integers.

Algorithm 5.4 C version of the convolution routine.

```

#include <stdlib.h>
conv(char *im, int planes, int rows, int cols, float c1, float c2, float c3)
/* C version of a convolution routine */
{
    int i, j, p, temp;
    int planestep=rows*cols;
    char * plane, * buffplane;
    char * buff = malloc( rows*planes*cols);
    for (p=0;p<planes;p++){
        plane = &im[p*planestep];
        buffplane= &buff[p*planestep];
        /* convolve horizontally */
        for(i=0;i<rows;i++){
            for(j=1;j<(cols-1);j++) {
                temp= plane[i*cols+j-1]*c1+plane[i*cols+j]*c2+plane[i*cols+j+1]*c3;
                if (temp<0){temp=0;}
                else if (temp>255) { temp=255;} ;
                buffplane[i*cols+j]=temp;
            }
            buffplane[i*cols]=plane[i*cols];
            buffplane[i*cols+cols-1]=plane[i*cols+cols-1];
        }
        /* convolve vertically */
        for(j=0;j<cols;j++) {
            for(i=1;i<rows-1;i++){
                temp= buffplane[(i-1)*cols+j]*c1+buffplane[i*cols+j]*c2+buffplane[(1+i)*cols+j]*c3;
                if(temp<0){temp=0;}
                else if (temp>255) { temp=255;} ;
                plane[i*cols+j]=temp;
            }
            plane[j]=buffplane[j];
            plane[(rows-1)*cols+j]=buffplane[ (rows-1)*cols+j];
        }
    }
    free(buff);
}

```

5.6.1 Range checking

When arrays are indexed, the compiler plants run time checks to see if the indices are within bounds. In many cases the optimiser is able to remove these checks, but in those cases where it is unable to do so, some performance degradation can occur. Range checks can be disabled or enabled by the compiler directives.

```
{ $r- } { disable range checks }  
{ $r+ } { enable range checks }
```

Performance can be further enhanced by the practice of declaring arrays to have lower bounds of zero. The optimiser is generally able to generate more efficient code for zero based arrays.

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