

winch diameter $r_{\text{cyl}} := 6\text{mm}$

winch cog pitch diameter $r_{\text{wheel}} := \frac{130\text{mm}}{2} = 65\text{mm}$

drive cog pitch diameter $r_{\text{cog}} := \frac{7.8\text{mm}}{2} = 3.9\text{mm}$

angle per cog step $\text{ang}_{\text{cog}} := 1.8\text{deg}$

wheel angle per cog step $\text{ang}_{\text{wheel}} := \text{ang}_{\text{cog}} \cdot \frac{r_{\text{cog}}}{r_{\text{wheel}}} = 0.108\text{deg}$

cable displaced per cog step $\text{disp}_{\text{cyl}} := \pi \cdot 2 \cdot r_{\text{cyl}} \cdot \frac{\text{ang}_{\text{wheel}}}{360\text{deg}} = 11.31\text{mm}$

number of steps per mm $\text{step}_{\text{mm}} := \frac{1\text{mm}}{\text{disp}_{\text{cyl}}} = 88.419413$

range of total displacement $\frac{28\text{deg}}{\text{ang}_{\text{wheel}} \cdot \text{step}_{\text{mm}}} = 2.9322$

Spring rate - non-stainless

0.3mm wire, 3mm OD, 40mm length, 13 total coils (11 active coils)

[ref. <https://www.acxesspring.com/compression-spring-calculations.html>]

$$k := 0.371 \frac{\text{N}}{\text{mm}}$$

PTFE coefficient friction $\mu := 0.1$

Contact angle $\phi := 90\text{deg}$

$$T_{\text{hold}} := 1\text{N}$$

$$T_{\text{load}} := T_{\text{hold}} \cdot e^{\mu \cdot \phi} = 1.17\text{N}$$

difference in force can then be used to evaluate the stretch in the wire between pulling and releasing (backlash). In combination with the stiffness of the lever mechanism